

## A-5 4 Loops

### A-5-1 Description

The following drawings below are provided to help the user to better understand all the information concerning the specific control strategy and, in particular:

- Project Tasks (POU) Organization and Order;
- Block diagram representation;
- Set of display panels used within the application;
- Application examples;
- I/O table related to the signals managed from/to the field.

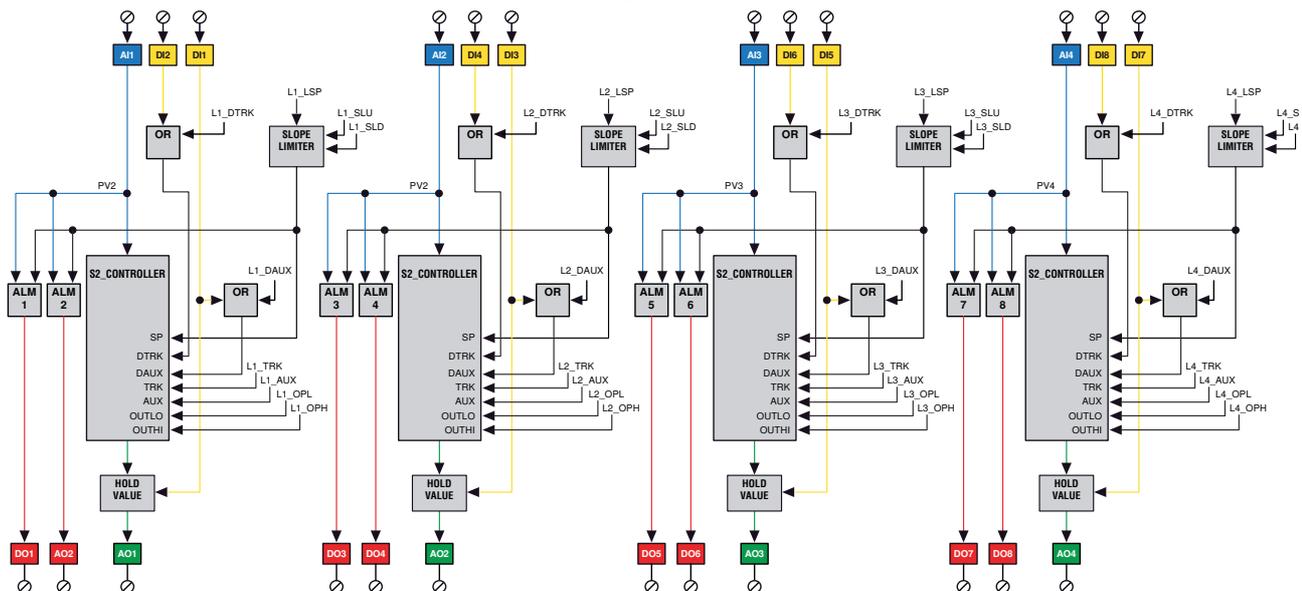
### A-5-2 Project Tasks (POU) Organization and Order

In order to obtain the proper operations coming with the functions of the strategy, it is necessary to link the tasks that have been developed as follows:

1. **Four\_Loops\_Vars.STD.POE** Global Variables declaration file;
2. **Four\_Loops\_Vars.DIR.POE** Direct Variables declaration file;
3. **Four\_Loops\_Values\_Mngt.ST** Variables application pre-set operations;
4. **Four\_Loops\_IO\_Mngt.CFC** I/O conditioning operations;
5. **Four\_Loops\_Common\_Oprs.ST** Application overall general operations;
6. **Four\_Loops\_1\_Mngt.CFC** Specific 4 loops process control operations;
7. **Four\_Loops\_2\_Mngt.CFC** Specific 4 loops process control operations;
8. **Four\_Loops\_3\_Mngt.CFC** Specific 4 loops process control operations;
9. **Four\_Loops\_4\_Mngt.CFC** Specific 4 loops process control operations;
10. **Four\_Loops\_Pages.CFC** Overall display Pages management
11. **Four\_Loops\_Tags.CSV** Display pages specific tags excel CSV file.

### A-5-3 Block Diagram

The following diagram provides an overall understanding of the process control and logic that have been arranged for the specific purpose. For this reasons the function block representation has been simplified to enhance readability and the specific functionalities meaning.



This configuration provides a 4 independent basic PID loops, including output forcing mode and 2 alarms that behave according to the working mode desired for each of the ALARM\_ADV function block.

The descriptions that follow refer to Loop1 only due to the fact all of them are identical. They differ only by the specific I/O managed by themselves.

**Control** The AI1 Controlled variable is acquired, filtered, corrected and converted into the desired engineering unit by the specific and dedicated MP\_AI\_MNGT\_ADV function block with Out of Range detection. Then, it is managed by the dedicated S2\_CONTROLLER function block which performs the PID calculation accordingly to the desired SP. It generates the control output value to drive the actuator which has to be connected to the AO1 analogue output.

**Forcing Modes** These operations are alternative to the S2\_CONTROLLER PID output calculation. The Tracking mode sets the control output to the constant value, editable from the specific Configuration page, until the DI2 is activated or the DTRK command coming from the dedicated front panel whilst the Hold function freezes the loop control output while the DI1 digital input is activated.

DI1	DI2	Selected Value
OFF	OFF	No forcing
OFF	ON	Output Tracking
ON	OFF	Output Hold
ON	ON	Output Tracking

**Alarms** Two alarms are implemented by additional ALARM\_ADV function blocks on the AI1 Controlled variable. The status is reported as digital output through DO1 and DO2.

#### A-5-4 Graphic Displays



The pictures above show the different types of display panels, providing the most effective interface for this strategy configuration. After the Custom page, XXX

more panel pages consisting in a 4 bargraph display, the alarm list and the Forcing mode list are intended to provide a quite complete interface for this configuration.

The panel with the 4 bargraphs provides a complete view of all the 4 loops, with a fine level of details on the most important parameters.

If you want to operate on a loop, first you have to select it, by pressing the  button. The loop selected is highlighted by the background colour of the specific Tag that changes from dark grey to light blue. Once the loop has been selected, it is possible to change the SP and/or the A/M station operating mode. Furthermore, the parameters shown in the upper part of the panel relates to the selected loop.

The status of the alarms is displayed by the scrolling bar present on all the pages available within an application. When an alarm becomes active, the related alarm description scrolls continuously, to alert the operator. Anyway, the operator can get a more detailed view of the alarms, looking at the specific "Alarms & Events" panel pages.

### **A-5-5 Applications**

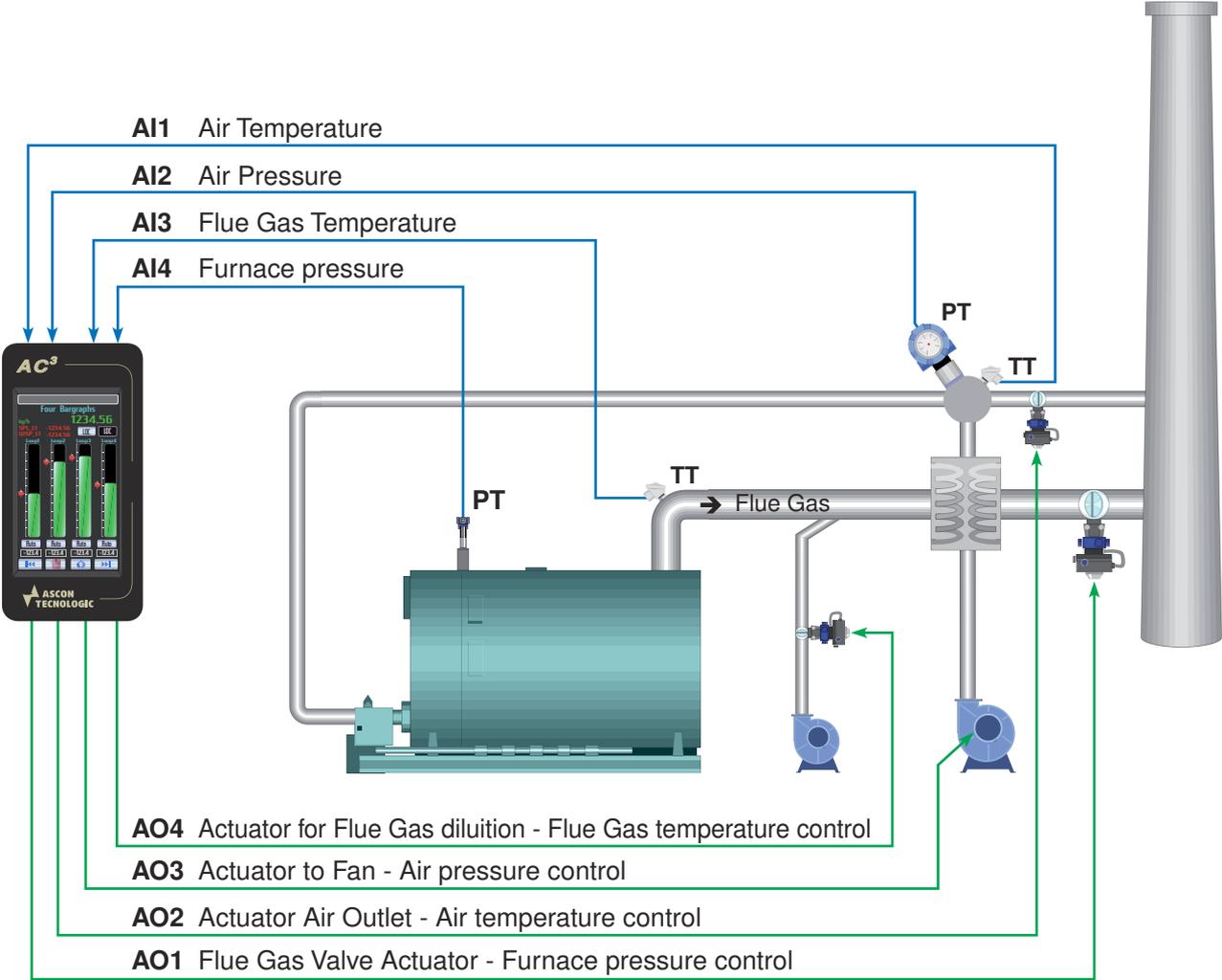
This easy to use configuration is for simple applications, where standard PIDs are required to control up to 4 independent variables in just one box, with perfectly identical characteristics.

Furthermore, the loops have some additional functionalities, such as alarms and output forcing modes, to achieve more advanced results than a basic PID.

A typical example of a process where this configuration can be applied, is the control of a combustion heating furnace. The loops could be used to control:

- Air pressure;
- Air temperature;
- Furnace pressure;

- Co-generator flue gas temperature.



### A-5-6 Signals I/O Table

I/O	Terminals	Type	Meaning
<b>AI1</b>	E1 +/F1 -	4... 20 mA	Loop1 Controlled Variable
<b>AI2</b>	E2 +/F2 -	4... 20 mA	Loop2 Controlled Variable
<b>AI3</b>	E3 +/F3 -	4... 20 mA	Loop3 Controlled Variable
<b>AI4</b>	E4 +/F4 -	4... 20 mA	Loop4 Controlled Variable
<b>AI5</b>	E5 +/F5 -	4... 20 mA	Not Used - Available
<b>AI6</b>	E6 +/F6 -	4... 20 mA	Not Used - Available
<b>AI7</b>	E8 +/F8 -	4... 20 mA	Not Used - Available
<b>AI8</b>	E10 +/F10 -	4... 20 mA	Not Used - Available
<b>AO1</b>	E11 +/F11 -	4... 20 mA	Loop1 Control Output
<b>AO2</b>	E12 +/F12 -	4... 20 mA	Loop2 Control Output
<b>AO3</b>	E13 +/F13 -	4... 20 mA	Loop3 Control Output
<b>AO4</b>	E14 +/F14 -	4... 20 mA	Loop4 Control Output
<b>DI1</b>	A2	NO Digital Input	Loop1 Control Output Hold
<b>DI2</b>	A3	NO Digital Input	Loop1 Control Output Tracking
<b>DI3</b>	A4	NO Digital Input	Loop2 Control Output Hold
<b>DI4</b>	A5	NO Digital Input	Loop2 Control Output Tracking
<b>DI5</b>	B2	NO Digital Input	Loop3 Control Output Hold
<b>DI6</b>	B3	NO Digital Input	Loop3 Control Output Tracking
<b>DI7</b>	B4	NO Digital Input	Loop4 Control Output Hold
<b>DI8</b>	B5	NO Digital Input	Loop4 Control Output Tracking
<b>DO1</b>	A6	NO Digital Output	Loop1 Alarm_1 Status
<b>DO2</b>	A7	NO Digital Output	Loop1 Alarm_2 Status
<b>DO3</b>	A8	NO Digital Output	Loop2 Alarm_3 Status
<b>DO4</b>	A9	NO Digital Output	Loop2 Alarm_4 Status
<b>DO5</b>	B6	NO Digital Output	Loop3 Alarm_5 Status
<b>DO6</b>	B7	NO Digital Output	Loop3 Alarm_6 Status
<b>DO7</b>	B8	NO Digital Output	Loop4 Alarm_7 Status
<b>DO8</b>	B9	NO Digital Output	Loop4 Alarm_8 Status