

YASKAWA

MPiec Series

Machine Controller



EASY FOR YOU. CONSISTENT FOR EVERYONE.



A Familiar Programming Standard

MotionWorks IEC complies with IEC 61131-3, and provides five globally recognized standard programming languages. It includes motion function blocks that adhere to the PLCopen standard. Experienced control engineers will find this software comfortably familiar, and learning to program with MotionWorks IEC has never been easier.



Built-in YASKAWA Toolboxes

Yaskawa toolboxes make programming common functions so easy, it's like having a YASKAWA engineer working by your side. Development time is reduced because standard code elements are already written and ready for use.



Easy Connectivity, Worldwide

An MPiec controller is your gateway to full control of a machine at any remote location with internet access. Keep a constant finger on the pulse of machine operation, from your own factory floor or anywhere worldwide.



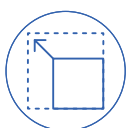
A Reusable Code Library

Import and re-use previously developed logic to speed up new projects. Re-use your own work or draw on logic created by others.



Web Server Updates

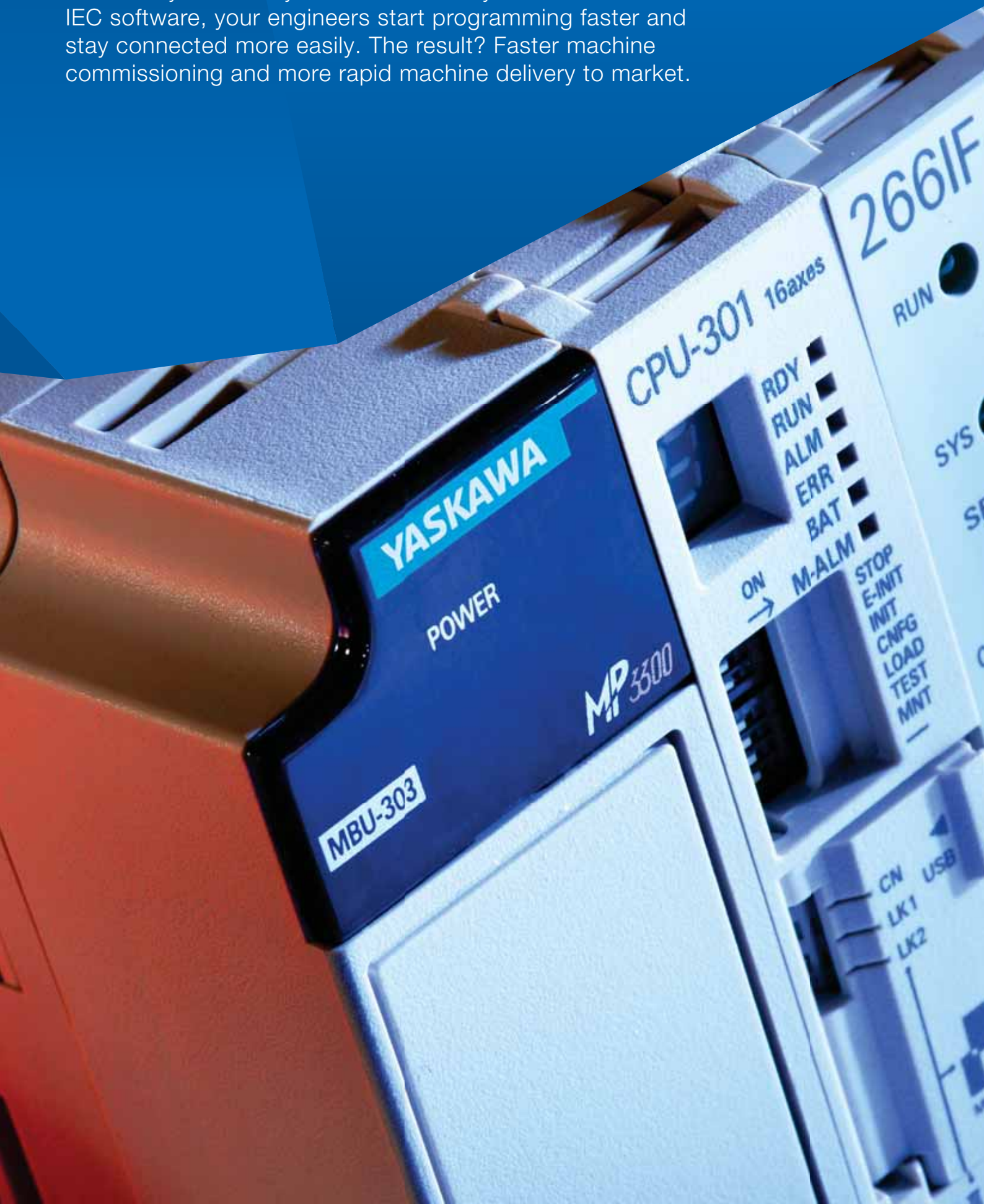
MPiec controllers allow loading of programs and updating of firmware from any web browser, with no other software required. Browser-based controller status data helps reduce maintenance time and cost.



Scalability

All our single-axis to multi-axis MPiec controllers utilize the same MotionWorks IEC software platform, making programming and maintenance consistent for all machine sizes.

Today's customers need to keep a finger on the pulse of their machines at all times. Success means maintaining peak productivity, total reliability and endless freedom to interact with the systems they control. With easy-to-learn MotionWorks IEC software, your engineers start programming faster and stay connected more easily. The result? Faster machine commissioning and more rapid machine delivery to market.



MPiec Machine Controller Hardware

MPiec Machine Controllers offer a wide range of hardware for applications ranging from 1 to 62 axes. All controllers are equipped with the reliable MECHATROLINK motion network.

MP2600iec

- Processor Speed: 200 MHz
- Motion Network: Dual Port RAM access
- Motion Networks Speed: As fast as 1 ms
- Network Capability: OPC, EtherNet/IP, Modbus TCP
- Axis Count: 1.5
- Option Card Slots: None (On board I/O)



MP2300Siec / MP2310iec

- Processor Speed: 240 MHz
- Motion Network: MECHATROLINK-II
- Motion Networks Speed: As fast as 0.5 ms
- Network Capability: OPC, EtherNet/IP, Modbus TCP
- Axis Count: 4, 8 or 16
- Option Card Slots: 1 or 3



MP3300iec

- Processor Speed: 400 MHz / 800 MHz
- Motion Network: MECHATROLINK-III
- Motion Networks Speed: As fast as 0.25 ms
- Network Capability: OPC, EtherNet/IP, Modbus TCP
- Axis Count: 4, 8, 20 or 32
- Option Card Slots: 1, 3 or 8



MP3200iec

- Processor Speed: 1 GHz
- Motion Network: MECHATROLINK-III
- Motion Networks Speed: As fast as 0.25 ms
- Network Capability: OPC, EtherNet/IP, Modbus TCP
- Axis Count: 8, 16, 32 or 62
- Option Card Slots: 3, 5 or 8



VIPA SLIO I/O

If you've wished that Input/Output could be FASTER and EASIER, VIPA SLIO is for you. The new YASKAWA decentralized I/O system is full of features that make connection simpler and I/O functions more efficient.

Easy Web Interface

SLIO diagnostic and status information is accessible through a web interface, delivering complete system status data from any EtherNet/IP or Modbus TCP field-bus module into a standard browser. Remote access via Internet is also available.



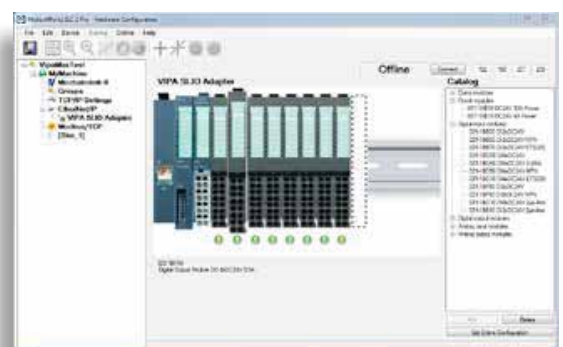
High Speed Backplane Bus

Achieve reaction times as fast as 20 microseconds with VIPA SLIO's high speed backplane bus. Connect as many as 64 modules at a time, while maintaining speeds up to 48 Mbit/s.



One-touch Hardware Configurator

VIPA SLIO puts an end to hours of tedious manual I/O configuration. The MotionWorks IEC VIPA SLIO Hardware Configurator sets up a complete I/O system with the touch of a single button.



Getting Connected

Easily connect all parts of your machine without a hassle - from machine controllers, parameter and monitor software, inverter drives, servo drives, VIPA HMIs, SLIO I/Os, to Motoman robots from YASKAWA.



VIPA HMI



Software



Ethernet

EtherNet/IP



MPiec Controller



SERVOPACK



SERVOPACK



SERVOPACK



Rotary Motors



Linear Motors



Direct Drive Motors



A controller that gets you to the position you want, when you want it:

- Deterministic high speed MECHATROLINK network
- MECHATROLINK retry function
- Dedicated CPU for your motion needs
- High CPU scan rate

Program all of your controllers the same way every time:

- Standard IEC 61131-3 programming languages
- Reusable PLCopen function blocks
- Reusable standard Yaskawa toolboxes
- Decades of high quality motion experience

Your entire machine at your fingertips with Yaskawa controllers:

- Sigma-5 servos via MECHATROLINK
- Built in web server
- OPC server
- EtherNet/IP
- Modbus TCP
- Wide range of HMIs and I/Os



IEC-based Motion Programming

Only a few programming languages provide an environment for simply coding all of the functionality of a modern automated machinery. MotionWorks® IEC encourages the programmer to take advantage of the best of several programming languages within one development package.

Reusable Code and YASKAWA Application-specific Toolboxes

Drawing on decades of motion experience, Yaskawa created toolboxes with pre-developed code for specific applications.

Leverage Yaskawa expertise to minimize programming time and effort. Libraries also enable importing and re-use of logic you've previously developed, saving even more time on subsequent projects.

MotionWorks IEC 3

- 10 different CAM function blocks available
- Open standards like PackML for packaging
- Supports implementation according FDA 21FR Part 11

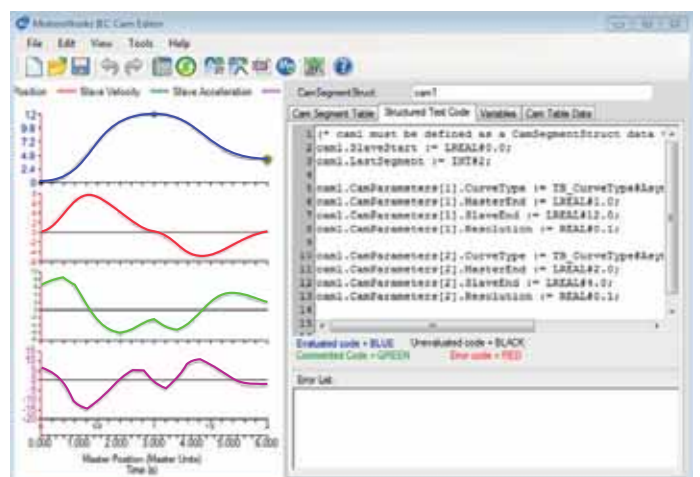
Benefits:

- Rapid realisation of machine functions
- Reliability by validated function blocks
- Toolkit function blocks enable import and reuse of previously developed logic

CAM Editor

- Supports 11 cam curve types
- Can read and write IEC 61131-3 code to generate cam tables at run time
- Supports multi step blended Cams and Cam in and out

Function	Motion Works IEC	
	Express	Professional
Number of Tasks	1	16
Number of Resources	1	1
IEC 61131-3 Languages		
Ladder Diagram	●	●
Function Block	●	●
Structure Text	●	●
Sequential Function Chart	–	●
Instruction List	–	●
POU Grouping	–	●
Configurable Task Priority	–	●
Configurable I/O Assignment	–	●
Auto Save Setting	–	●
Debug PowerFlow	–	●
Password Protection	–	●
Project Comparison	–	●



For a wide Range of Applications

Using the MP3000iec Series of machine controllers improves handling and performance in a broad range of applications. With up to 52 MB of memory for user-data and up to 1 GHz CPU speed, even very complex applications with up to 62 axes can be controlled.



Handling Applications



Textile Applications



Food Packaging Applications



Filling and Packaging of Beverages



Woodworking Applications



Digital Printing Applications

System components

MP2300Siec & MP2310iec

Common Options MP2300Siec		
MP2300Siec Controller CPU with 1 Option Module Slot	MECHATROLINK-II, EtherNet/IP and Modbus/TCP communications	
	16 axis, one option module	PMC-U-MP23S16
MP2310iec Controller CPU with 3 Option Module Slots	16 axis, three option modules	PMC-U-MP23116
Accessories	Replacement Battery	JZSP-BA01
	DIN Rail Clips (2 per set)	JEPMC-OP300
	Option Slot Cover	JEPMC-OP2300
	Panel Mounting Bracket for screw mounting	JEPMC-OP2300S-E
Communication		
I/O Option Cards	Analog Inputs (AI-01)	JAPMC-AN2300
	Analog Outputs (AO-01)	JAPMC-AN2310
	Digital Output Module (DO-01)	JAPMC-DO2300
	Digital I/O Module (LIO-01)	JAPMC-IO2300-E
	Digital I/O Module (LIO-02)	JAPMC-IO2301-E
	Digital I/O Module (LIO-04)	JAPMC-IO2303
	Digital I/O Module (LIO-05)	JAPMC-IO2304
Multi-Function I/O Module (LIO-06)	JAPMC-IO2305-E	
Cables		
MECHATROLINK-II Cables	Cables available in different length	JEPMC-W6003-□□-E-G5
		□□: Cable Length (A5: 0.5 m, 01: 1.0 m, 03: 3.0 m, 05: 5.0 m, 10: 10.0 m, 20: 20.0 m)
Option Card Cables (Pigtail)	AI-01	JEPMC-W6080-□□-E
	AO-01	JEPMC-W6090-□□-E
	LIO-01/02	JEPMC-W2061-□□-E
	LIO-04/05	JEPMC-W6060-□□-E
	LIO-06	JEPMC-W2064-□□-E
		□□: Cable Length (A5: 0.5 m, 01: 1.0 m, 03: 3.0 m)
Network		Model code
Network Termination Resistor	Two (2) required to terminate ends of network (one included with MP2300Siec)	JEPMC-W6022

MP3300iec & MP3200iec

Common Options MP3300iec		
MP3300iec Controller CPU	MECHATROLINK-III, EtherNet/IP and Modbus/TCP communications	
	CPU card with 4 axis capability (Standard Performance, 400 MHz)	PMC-U-MP33004
	CPU card with 8 axis capability (Standard Performance, 400 MHz)	PMC-U-MP33008
	CPU card with 20 axis capability (Standard Performance, 400 MHz)	PMC-U-MP33020
	CPU card with 20 axis capability (Medium Performance, 800 MHz)	PMC-U-MP33320
	CPU card with 32 axis capability (Medium Performance, 800 MHz)	PMC-U-MP33332
Power Supply & Base Unit Rack	24 VDC power supply with single slot base unit rack	JEPMC-BU3304-E
	24 VDC power supply with three slot base unit rack	JEPMC-BU3303-E
	24 VDC power supply with eight slot base unit rack	JEPMC-BU3302-E
	230 VAC power supply with eight slot base unit rack	JEPMC-BU3301-E
Accessories	Replacement Battery	JEPMC-BA3001
	Replacement CPU Faceplate	JEPMC-OP3301-1-E
	Option Slot Cover	JEPMC-OP3301-E
Common Options MP3200iec		
MP3200iec Controller CPU	MECHATROLINK-III, EtherNet/IP and Modbus/TCP communications	
	CPU card with 4 axis capability (High Performance, 1 GHz)	PMC-U-MP32004
	CPU card with 8 axis capability (High Performance, 1 GHz)	PMC-U-MP32008
	CPU card with 16 axis capability (High Performance, 1 GHz)	PMC-U-MP32016
	CPU card with 32 axis capability (High Performance, 1 GHz)	PMC-U-MP32032
	CPU card with 62 axis capability (High Performance, 1 GHz)	PMC-U-MP32062
Power Supply	100 - 200 VAC Input	JEPMC-PSA3012-E
	24 VDC	JEPMC-PSD3012-E
Base Unit Rack	3 Slot	JEPMC-BUB3003-E
	5 Slot	JEPMC-BUB3005-E
	8 Slot	JEPMC-BUB3008-E
Accessories	Replacement Battery	JEPMC-BA3001
	Replacement Power Supply Side Cover	JEPMC-OP3001
	Replacement Base Unit Rack Side Cover	JEPMC-OP3002
	Option Slot Cover	JEPMC-OP2300
Communication		
I/O Option Cards	Analog Inputs (AI-01)	JAPMC-AN2300
	Analog Outputs (AO-01)	JAPMC-AN2310
	Digital Output Module (DO-01)	JAPMC-DO2300
	Digital I/O Module (LIO-01)	JAPMC-IO2300-E
	Digital I/O Module (LIO-02)	JAPMC-IO2301-E
	Digital I/O Module (LIO-04)	JAPMC-IO2303
	Digital I/O Module (LIO-05)	JAPMC-IO2304
	Multi-Function I/O Module (LIO-06)	JAPMC-IO2305-E
Cables		
MECHATROLINK-III Cables	Cables available in different length □□: Cable Length (A2: 0.2 m, A5: 0.5 m, 01: 1.0 m, 02: 2.0 m, 03: 3.0 m, 04: 4.0 m, 05: 5.0 m)	JEPMC-W6012-□□-E
Network		Model code
MECHATROLINK-III Network Accessories	Hub, 8 Slave Ports	JEPMC-MT2000-E
	Adaptor, Ethernet to Mechatrolink	JEPMC-MT2020-E
	I/O Module; 64 In 64 Out	JEPMC-MTD2310-E
	Analog Module; 8 In (for MP3200iec only)	JEPMC-MTA2900-E
	Analog Module; 4 Out (for MP3200iec only)	JEPMC-MTA2910-E

Specification



MP2300Siec

Operating Environment	
Ambient Temperature	0 °C to 55 °C
Humidity	max. 95% RH (non condensing)
Storage Temperature	-25 °C to 85 °C
Altitude	2,000 m above sea level or lower
Pollution Level	Conforms to JIS B 3502 Pollution Degree 1
Corrosive Gas	There must be no combustible or corrosive gas
Mechanical Conditions	
Vibration Resistance	Conforming to JIS B 3502:
	10 to 57 Hz with single amplitude of 0.075 mm
	57 to 150 Hz with fixed acceleration of 9.8 m/s ² 10 sweeps each in X, Y, and Z directions (sweep time: 1 octave/min.)
Shock Resistance	Size of shock: Peak acceleration of 147 m/s ² (15 G)
	Duration: 11 ms 3 times each in the X, Y, and Z directions
Electrical Conditions	
Noise Resistance	Conforming to EN 61000-6-2, EN 55011 (Group 1, Class A)
	Power supply noise (FT noise): 2 kV min., for one minute
	Radiation noise (FT noise): 1 kV min., for one minute
Ground	Ground to 100 Ω max.
Cooling Method	Natural cooling
Controller Details	
CPU Speed	240 MHz SH4
Number of option module slots	1
User Variable Memory	1.75 MB
Power Unit	Input Voltage: 24 Vdc (±20%)
	Input Current: 1.0 A max (at rated input/output)
	Current Consumption: 1.0 A max
	Battery: Battery for memory retention attachable
Motion Network	MECHATROLINK-II: 1 channel
	SERVOPACK and I/O for up to 20 slave nodes connectable (SERVOPACK for up to 16 axes)
	Baud rate: 10 Mbps (MECHATROLINK-II)
Communication Function	Ethernet: 10Base-T or 100Base-TX
Ethernet Protocols	Ethernet/IP and Modbus TCP/IP standard on all units
Software	MotionWorks IEC Express
	MotionWorks IEC Pro

MP2600iec



Operating Environment	
Ambient Temperature	0 °C to 55 °C
Humidity	max. 95% RH (non condensing)
Storage Temperature	-25 °C to 85 °C
Altitude	1,000 m above sea level or lower
Pollution Level	Conforms to JIS B 3502 Pollution Degree 2
Corrosive Gas	There must be no combustible or corrosive gas
Mechanical Conditions	
Vibration Resistance	Conforming to JIS B 3502: 4.9 m/s ²
Shock Resistance	19.6 m/s ²
Controller Details	
CPU Speed	200 MHz
User Variable Memory	4 MB
Inputs	8 programmable digital inputs 1 ch., +/- 10 V, 16 bit analog input
Outputs	8 programmable digital outputs 1 ch., +/- 10 V, 16 bit analog output
Pulse Counter	RS-422-compatible pulse counter input (quadrature, pulse and direction, and up/down counter modes) with 5, 12, and 24 V position latch inputs
Communication Function	Ethernet: 2x 100Base-TX
Ethernet Protocols	Ethernet/IP and Modbus TCP/IP; OPC (Client and Server required)
Software	MotionWorks IEC Express MotionWorks IEC Pro
Servo Details	
Sequence Input	Number of Inputs: 7 (1 registration input latches external encoder in 5 μs) Functions: The signal allocation and positive/negative logic can be modified. Forward run prohibited (P-OT), reverse run prohibited (N-OT), forward torque limit (/P-CL), reverse torque limit (/N-CL), general-purpose input signal (/SI0 to /SI6)
Sequence Output - Fixed	Servo Alarm (ALM)
Sequence Output - Allocated	Number of Outputs: 3 Functions: The signal allocation and positive/negative logic can be modified. Positioning completion (/COIN), speed coincidence detection(/V-CMP), servomotor rotation detection (/TGON), servo ready (/S-RDY), torque limit detection (/CLT), speed limit detection(/VLT), brake (/BK), warning (/WARN), near (/NEAR)

Specification

MP3200iec



Operating Environment	
Ambient Temperature	0 °C to 55 °C
Humidity	max. 95% RH (non condensing)
Storage Temperature	-25 °C to 85 °C
Altitude	2,000 m above sea level or lower
Pollution Level	Conforms to JIS B 3502 Pollution Degree 1
Corrosive Gas	There must be no combustible or corrosive gas
Mechanical Conditions	
Vibration Resistance	Conforming to JIS B 3502:
	10 to 57 Hz with single amplitude of 0.075 mm
	57 to 150 Hz with fixed acceleration of 9.8 m/s ² 10 sweeps each in X, Y, and Z directions (sweep time: 1 octave/min.)
Shock Resistance	Size of shock: Peak acceleration of 147 m/s ² (15 G)
	Duration: 11 ms 3 times each in the X, Y, and Z directions
Electrical Conditions	
Noise Resistance	Conforming to EN 61000-6-2, EN 55011 (Group 1, Class A)
	Power supply noise (FT noise): 2 kV min., for one minute
	Radiation noise (FT noise): 1 kV min., for one minute
Ground	Ground to 100 Ω max.
Cooling Method	Natural cooling or forced-air cooling
Controller Details	
CPU Speed	1 GHz PowerPC
Number of option module slots	0, 3, 5 or 8
User Variable Memory	52 MB
Power Unit	Input Voltage: Two options available: 24 VDC or 100/200 VAC
	Input Current: DC power: 5.0A, AC power: 4.0A (at rated input/output fully loaded with option cards)
	Battery: Battery for memory retention attachable at the bottom of the CPU unit
Motion Network	MECHATROLINK-III: 1 channel, 2 connectors
	SERVOPACK and I/O for up to 62 slave nodes connectable (SERVOPACK for up to 62 axes)
	Baud rate: 100 Mbps (MECHATROLINK-III)
Communication Function	Ethernet: 10Base-T or 100Base-TX
Ethernet Protocols	Ethernet/IP and Modbus TCP/IP standard on all units, User specific protocols can be written using Y_DeviceComm firmware library
Software	MotionWorks IEC Express
	MotionWorks IEC Pro

MP3300iec



Operating Environment	
Ambient Temperature	0 °C to 60 °C (forced cooling is required if 55°C is exceeded.)
Humidity	max. 95% RH (non condensing)
Storage Temperature	-25 °C to 85 °C
Altitude	2,000 m above sea level or lower
Pollution Level	Conforms to JIS B 3502 Pollution Degree 2
Corrosive Gas	There must be no combustible or corrosive gas
Mechanical Conditions	
Vibration Resistance	Conforming to JIS B 3502:
	Continuous vibration: 5 to 9 Hz with single amplitude of 1.75 mm
	9 to 150 Hz with fixed acceleration of 4.9 m/s ²
	Intermittent vibration: 5 to 9 Hz with single-amplitude of 3.5 mm
	9 to 150 Hz with fixed acceleration of 9.8 m/s ²
Shock Resistance	10 sweeps each in X, Y, and Z directions for both intermittent and continuous vibration
	Size of shock: Peak acceleration of 147 m/s ² (15 G) Duration: 11 ms 3 times each in the X, Y, and Z directions
Electrical Conditions	
Noise Resistance	Conforming to EN 61000-6-2, EN 61000-6-4 and EN 55011 (Group 1, Class A)
	Power supply noise (FT noise): 2 kV min., for one minute
	Radiation noise (FT noise): 1 kV min., for one minute
	Ground noise (impulse noise): 1 kV min., for 10 minutes
	Electrostatic noise (contact discharge method): 6 kV or more, 10 times
Ground	Ground to 100 Ω max.
Cooling Method	Natural cooling or forced-air cooling
Controller Details	
CPU Speed	400 MHz
Number of option module slots	1, 3 or 8
User Variable Memory	32 MB
Power Unit	Input Voltage: 24 Vdc
	Input Current: 1.0 A max (at rated input/output) for 1 slot module 1.5 A max (at rated input/output) for 3 slots module
	Battery: Battery for memory retention attachable at the bottom of the CPU unit
Motion Network	MECHATROLINK-III: 1 channel, 2 connectors
	SERVOPACK and I/O for up to 20 slave nodes connectable (SERVOPACK for up to 20 axes)
	Baud rate: 100 Mbps (MECHATROLINK-III)
Communication Function	Ethernet: 10Base-T or 100Base-TX
Ethernet Protocols	Ethernet/IP and Modbus TCP/IP standard on all units, User specific protocols can be written using Y_DeviceComm firmware library
Software	MotionWorks IEC Express
	MotionWorks IEC Pro

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