## FUZZY Universal Controller

 with total configuration 48x96 DIN,XF Series
INSTRUCTION MANUAL
MIU.XF- 2/96.10/E
COD J30-154-1AXF ING


## Ascon Tecnologic Srl

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## 1•IDENTIFICATION OF MODEL

Thank you for choosing an ASCON controller
The instruments of the XF series belong to the last generation of microprocessor based controller, are universal, very powerful but simple to use.
They are fitted with AUTO-TUNE , an auxiliary for system start-up, and serial communication for introduction into a distributed control network. They are complete because all possible variables are always present. Configuration of the instrument permits determination of the operating mode according to the application required.

### 1.1 Identification of model



### 1.2 Configuration code

Configuration code
EFGH-ILMN /

Beginning and end of scale

Model code

| $\begin{gathered} \frac{\pi}{\sigma} \\ \stackrel{2}{2} \\ \frac{\pi}{\sigma} \end{gathered}$ | Input X | E |
| :---: | :---: | :---: |
|  |  | F |
|  | Main output Y1 | G |
|  |  | H |
|  | Auxiliary output Y2 | I |
|  | Auxiliary output Y3 | L |
|  | Retransmission output Y4 | M |
|  | Set point W | N |

Beginning and end of scale (for configurable scales only) 0 P

The controller is normally configured in the factory.


In order to configure the controller, follow the configuration procedure reported in the enclosed leaflet

## 2• FUNCTION OF KEYS AND DISPLAYS



| 1 - Measure $X$ |
| :--- | :--- |
| (green) |$\quad$| The value of measure X is expressed in engineering |
| :--- |
| units. |
| If above end of scale |
| If below beginning of scale |
| - In programmation: displays parameter values |
| - In configuration: displays the values of the 1 st part |
| of the configuration code (see enclosed leaflet) |

## 2•FUNCTION OF KEYS AND DISPLAYS

## LEDS FOR OUTPUT STATE



LEDS FOR OPERATING STATE

| 9 - Manual (green) | Light in Manual operation |
| :---: | :---: |
| MAN |  |
| 10- Remote (green) | Light when the Remote Set point is operating (if off, the operating Set point is the Local one) |
| REM |  |
| 11- Auto-Tune (green) | Light when Auto-Tune is AT in course |
| AT |  |
| 12-Serial comm. (green) | Permanently light when the serial communication is enabled to write. Flashes with signal in transit |
| SCI |  |
|  | With output Y 3 active and configured as Loop Break Alarm, the front displays X and W are flashing (see p. 15) |

## 2•FUNCTION OF KEYS AND DISPLAYS

| KEYS |  |  |
| :---: | :---: | :---: |
| 13- Set Point | configuration: <br> 1 Local used for: <br> - modifying the Local Set po <br> 1 Local + 1 Remote used for: <br> - modifying the Local Set poin <br> - passing from Local to Remo and viceversa (see enclosed <br> 1 Local + 4 storable used for: <br> - modifying the Local Set poi <br> - to recall the Local operating <br> - recalling the 4 memorized (see enclosed leaflet) | nt <br> e Set point leaflet) <br> nt <br> Set point Set points |
| 14- Digit selection | Selects the digit to be modified (see enclosed leaflet) In Manual operation, decrements the value of main output Y 1 | Keys for modifying numeric values of any data |
| 15- Increment dig | Increments the value of the flashing digit, from 0... 9 In manual operation increments the value of main output Y 1 |  |
| 16. Functions | Permits access to menu of functions to be programmed | Keysfor data programming and processing |
| 17- Enter | Enter or Scroll of values and modes of operation |  |
| 18.-Auto/Man | Passage from Automatic to Manual operation and viceversa |  |

## 3-DIMENSIONS - INSTALLATION

## 3.1 - Overall dimensions (in compliance with DIN 43700)



## 3.2 - Panel installation




## 4•ELECTRICAL WIRING



## C•Effecting the connections



B • Freeing the terminals
1
Lift the plate to free
the pin


D • Protecting the terminal board


Although this controller is designed to resist the heaviest disturbances present in industrial environments (level IV of standard (IEC 801-4), it is advised to keep to the following precautions:


## Wiring diagram



## 1-Single power supply

| 12 | "Switching" type <br> - Standard: 100 to $240 \mathrm{Vac}-15 \%+10 \%$ <br> $250 \mathrm{Vac} \mathrm{max}$. |
| :--- | :--- |
| - for low tension: $24 \mathrm{Vac}-15 \%+10 \%$ |  |
| $24 \mathrm{Vdc} \pm 15 \%$ |  |
| Absorbed power 4VA |  |

## 2•"X" measurement input



Line: max. $150 \Omega$
B - For RTD Pt100

for 3-wire connection only
Line: $20 \Omega$ max. for wire

- Respect polarities
- For eventual extensions, use a compensated cable suitable for the type of thermocouple used
- The eventual screen is well earthed at only one end
- For 3-wire connection, use cables of same section (min. 1 sq.mm)
- For 2-wire connection, use cables of adequate section (min. 1.5 sq.mm.)

Note:
with a 15 m . probe-controller distance and a 1.5 sq. mm . section cable, the error is about $1^{\circ} \mathrm{C}$.


## 3 • Remote Set point input

Rin $=30 \Omega$ per mA
Rin $=330 \mathrm{~K} \Omega$ per V


| In current | $4 . .20 \mathrm{~mA}$ |
| :--- | :--- |
| In voltage | $0 . .10 \mathrm{Vdc}$ |



## $4 \cdot$ Logic inputs



An impulsive (2 sec. at least) closing of contacts C1, C2, C3, permits the selection AUTO or MAN, Local or Remote Set point and recalling the 4 memorized Set points

5 - Input potentiometer position (servomotors)


See calibration procedure on the enclosed sheet

| $6 \cdot$ Main output Y1 |  |  |
| :---: | :---: | :---: |
|  | Universal and galvanically isolated. 2 relays are simultaneously present for discontinuous output with single or dual action (HEAT:COOL), or for the floating output with 3 positions for servomotors and the signal for standard continuous output $4 . .20 \mathrm{~mA}$ (or $0 . .10 \mathrm{Vdc}$ ) which can also be Logic output 0/18Vdc). |  |
| A. Single with Relay | NA contact, capacity 5A/250Vac for resistive loads (transition $2 \times 10$ (coeff.5) min. at 5A/250Vac) |  |
|  |  |  |
| B • single in current | Continuous output $4 . .20 \mathrm{~mA}$ galvanically isolated |  |
|  |  |  |
| C. single in voltage | Continuous output $0 . .10 \mathrm{Vdc}$ galvanically isolated | Position the switch set inside the controller too |
|  |  |  |
| D - single logic | Output 0/18Vdc (20mA max.) galvanically isolated | -1 |
|  |  | (1) Continuous output 4... 20 mA Standard <br> (2) Continuous output $0 . . .10 \mathrm{Vdc}$ <br> (3) Logic output $0 . . .18 \mathrm{Vdc}$ |



## 4•ELECTRICAL WIRING

## 7 • Auxiliary outputs Y2 (see p. 14)



## $8 \cdot$ Retransmission output Y4 (option)



## $9 \cdot$ Serial communication (option)



Note
Zener 2,7 V Only for 20mA C.L.

Interface 20mA C.L. passive and galvanically isolated or RS485 port

Consult Directions for use "SERIAL COMMUNICATION SUPPLEMENT" MIU-CS/E supplied separately.

(1) - The Set point of $Y 2$ and $Y 3$ is not limited by the limits of the main Set point W1, but only by the scale span.

## Deviation with startup inhibition

|  | Active high (above) | Set point $\Delta \mathrm{W}$ (1) -300...+300 steps |
| :---: | :---: | :---: |
|  | Active low (under) |  |

## "Loop-Break-Alarm" LBA (control loop defect/interruption)

Any interruption in the connections or any anomaly in the operation of one of the control loop components, will cause the output Y3 to be energized after a few minutes and front display X and W will be flashing.
The alarm state will stop when the anomaly causing it stops or
depressing any key for silencing it.


## With ON - OFF action "LBA" feature is not available

In order to prevent tampering or inadvertent alterations of the configuration or of some important parameters at the programming stage, 2 passwords have to be entered.

### 6.1 Password of access to configuration 333



### 6.2 Password of access to the 3th parameter group ||| |



Introduction into the $3^{\text {th }}$ group
?

## Modifications may be carried out through:

commands from keyboard

external contacts on logic inputs

commands via serial


## With external contacts on logic inputs IL1, IL2, IL3

Impulsives closing for at least 2 sec., of contacts $\mathrm{C} 1, \mathrm{C} 2, \mathrm{C} 3$, permits modification of state or of Set point.

| IL1 | IL2 | IL3 | Type of modification |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| $\begin{aligned} & \overline{0} 0 \\ & \mathrm{C} 1 \end{aligned}$ | $\begin{aligned} & \overline{0} 0 \\ & \mathrm{C} 2 \end{aligned}$ | $\begin{aligned} & 00 \\ & \text { C3 } \end{aligned}$ | Version with only Local Set poin | Version with Set point (note1) <br> 1 Local + 4 Memorized | $\begin{gathered} \text { Version with } \\ \text { Set point } \\ 1 \text { Local + } 1 \text { Remote } \end{gathered}$ |
|  |  |  | No action |  |  |
| ON |  |  | No action |  | Passage from REMOTE to LOCAL |
|  | ON |  | Passage from AUTOMATIC to MANUAL |  |  |
| ON | ON |  | Passage from MANUAL to AUTOMATIC |  |  |
|  |  | ON | No action | Local Sp. = Memorized Sp. 1 | passage Local Sp. to Remote Sp. |
| ON |  | ON | No action | Local Sp. = Memorized Sp. 2 | - |
|  | ON | ON | No action | Local Sp. = Memorized Sp. 3 | - |
| ON | ON | ON | No action | Local Sp. = Memorized Sp. 4 | - |

Note 1: Is possible to fix the selected Set point holding closed the relative contacts. While they are closed is possible to make changment from Auto/Man or Man/Auto but it is not possible to change Set point

## 12•TECHNICAL DATA

| Accuracy (a25으 amb.) | $0.2 \% \pm 1$ digit (for input with RTD Pt100 and thermocouples) |  |  |
| :---: | :---: | :---: | :---: |
|  | $0.1 \% \pm 1$ digit (for input in current and voltage) |  |  |
| Input "X" (configurable) | RTD Pt100 | Pt100 $00{ }^{\circ} \mathrm{C}$, (IEC 751) | With configurable scale field |
|  | Thermocouples | J-K-S-R (IEC 584), L (DIN 43710) |  |
|  | Continuous current | $4 . .20 \mathrm{~mA}, 0 . .20 \mathrm{~mA}, \mathrm{Ri} 30 \Omega$ |  |
|  | Continuous voltage | $0 . .1 \mathrm{Vdc}, 0 . .10 \mathrm{Vdc}$, Ri $10 \mathrm{~K} \Omega$ |  |
| Auxiliary inputs | 3 of logic type (control of operating and Set point states) |  |  |
| Set point | 1 Local + 4 storable |  |  |
|  | Distinct ascent and descen gradient slope | $0.1 . .100 .0 \mathrm{digit} / \mathrm{min}$. |  |
|  | Higher and lower limit | from beginning to end of scale |  |
| Local/Remote <br> Set point | In current | $4 . .20 \mathrm{~mA}, \mathrm{Ri} 30 \Omega$ | Not isolated accuracy: $0.1 \%$ at $25^{\circ} \mathrm{C}$ |
|  | In voltage | $0 . .10 \mathrm{Vdc}$, Ri 330k $\Omega$ |  |
| Control mode | Algorithm | On - Off, PID, FUZZY, PID with I and D excludable actions. |  |
|  | Proportional band (P) | 0,5..999.9\% |  |
|  | Integral action time (I) | 0.1..100min., excludable |  |
|  | Derivative action time (D) | 0.01..10min., excludable |  |
|  | Cycle time | $1 . .200 \mathrm{sec}$. (for discontinuous control) |  |
|  | Hysteresis | 0.1..10\% (for on-off control) |  |
|  | Dead zone | $\pm 0 \ldots 5,0 \%$ for dual action (heat-cool) |  |
| Auto - Tune | For automatic parameter adjustment (One shot) |  |  |
| Auto/Man Station | With bumpless action, AUTO/MAN transfer via keyboard, logic input and serial communication. |  |  |


| $\begin{array}{\|l} \text { Main output } \\ \text { Y1 } \\ \text { (configurable) } \end{array}$ | Single or dual, with direct or reverse action |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Discontinuous | Relay with dual action 2 contacts NA, 5A/250Vac, $2 \times 10$ coeff. 5 transitions |  |  |
|  |  | Logic | $0.18 \mathrm{Vdc}, 20 \mathrm{~mA} \mathrm{max}$. (for static relays) | galvanically isolated |
|  | Continuous | Current | 4..20mA(450 2 max., 10 Volts max.) |  |
|  |  | Voltage | $0 . .10 \mathrm{Vdc}(450 \Omega \mathrm{~min} .20 \mathrm{~mA}$ max.) |  |
|  | Maximum output |  | 10..100\% ( $1^{\text {st }}$ channel $\triangle$ ) $-10 . .-100 \% ~\left(2 n^{\text {d }}\right.$ channel $\nabla$ ) |  |
| Auxiliary outputs Y2-Y3 (configurable) | Relay |  | 2 contacts NA, 5A/250Vac, $2 \times 10$ (coeff.5) transitions |  |
|  | Action mode |  | active high (above the set point) active low (below the set point) |  |
|  | Hysteresis |  | 0,1..10\% | with or without up) |
|  | Type of Set point |  | deviation $\quad \pm 300$ steps |  |
|  |  |  | band $0 . .300$ steps |  |
|  |  |  | independent from beginning to end of scale |  |
|  | Special functions |  | Loop-Break-Alarm (signal of control loop defect) |  |
| Retransmission output Y4 (option) | Current |  | $4 . .20 \mathrm{~mA}$ ( $450 \Omega$ max., 10 Vdc max.) | galvanically isolated |
|  | Voltage |  | $0 . .10 \mathrm{Vdc}(500 \Omega \mathrm{~min} ., 20 \mathrm{~mA} \mathrm{max}$. |  |
| Serial commnication (option) | Interface 20 mA C.L. passive and galvanically isolated (see manual MIU-CS/E) or RS485 port |  |  |  |
| Protections | Access to parameters |  | On three levels for: modification, indication only, no access |  |
|  | Immunity to disturbances level IV, standard IEC 801-4 |  |  |  |
|  | All significant data are stored in a non-volatile memory |  |  |  |
| Single power supply | Standard model |  | $100 . .240 \mathrm{~V}, 48 . .63 \mathrm{~Hz},-15 \%+10 \% \quad 250 \mathrm{Vac}$ max |  |
|  | Low voltage model |  | $24 \mathrm{~V}, 48 . .63 \mathrm{~Hz},-15 \%+10 \%$ or $24 \mathrm{Vdc} \pm 15 \%$ |  |
|  | Absorbed power |  | about 4VA |  |
| Auxiliary <br> power supply | $24 \mathrm{Vdc} \pm 10 \%, 20 \mathrm{~mA}$ max. for 2-wire or 3 or 4-wire transmitter |  |  |  |
| General features | Isolation group |  | C according to VDE 0110 |  |
|  | Climatic group |  | KWF according to DIN 40040 |  |
|  | Ambient temperature |  | $0 . . .50^{\circ} \mathrm{C}$., humidity $35 . . .85 u R \%$ |  |
|  | Protection |  | Front:IP54 standard (IP65 with Kit AXIP65-1) Cover: IP30, terminal board IP20 |  |
|  | Material |  | Self-extinguishing UL94V1 |  |
|  | Weight |  | about 480 g . |  |
|  | Dimensions |  | $48 \times 96$, depth 150 mm , according to DIN 43700 |  |

## GUARANTEE

The equipment is guaranteed free from manufacturing defects for 1 year after installation, for a maximum of 18 months after delivery.
Faults caused by use other than that described in these operating instructions are excluded from the guarantee.

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