

# CONTROLLER, PROGRAMMER AND SET POINT TRANSMITTER



33 X 72

KR5 model

Quick Guide • ISTR - FKR 5ENG00



viale Indipendenza 56, 27029 - Vigevano (PV) - ITALY

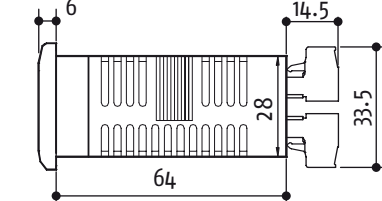
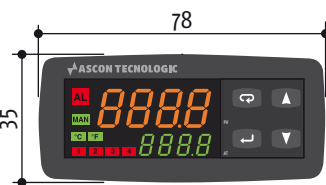
Tel.: +39 0381 698 71, Fax: +39 0381 698 730

internet site: www.ascontecnologic.com

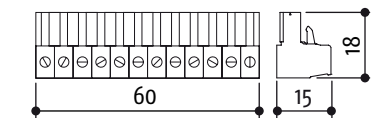
E-mail: sales@ascontecnologic.com

## 1. DIMENSIONS AND CUT-OUT (mm)

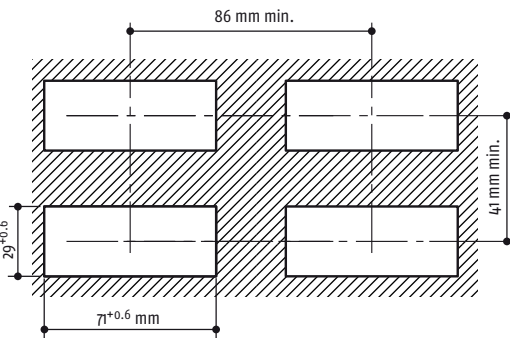
### Instrument with non removable terminals



### Removable terminals



### Panel cut-out



### Mounting requirements

This instrument is intended for permanent installation, for indoor use only, in an electrical panel which encloses the rear housing, exposed terminals and wiring on the back.

Select a mounting location having the following characteristics:

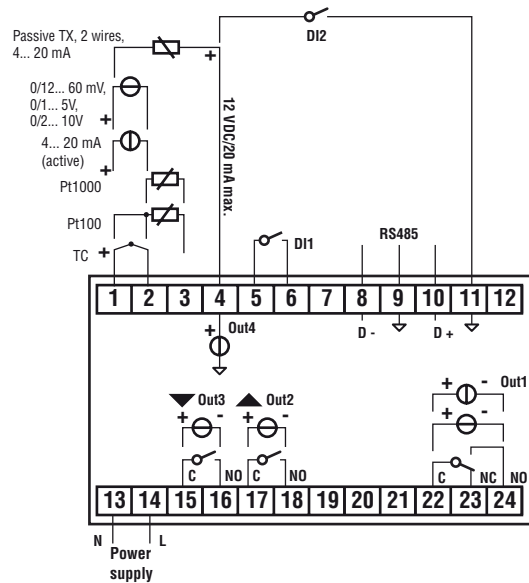
1. It should be easily accessible;
2. There is minimum vibrations and no impact;
3. There are no corrosive gases;
4. There are no water or other fluids (i.e. condensation);
5. The ambient temperature is in accordance with the operative temperature (0... 50°C);
6. The relative humidity is in accordance with the instrument specifications (20... 85%);

The instrument can be mounted on panel with a maximum thickness of 15 mm.

When the maximum front protection (IP65) is desired, the optional gasket must be mounted.

## 2. ELECTRICAL CONNECTIONS

### ELECTRICAL CONNECTIONS



#### Power supply voltage:

100... 240 Vac/24 Vdc/24 Vac;

**Out1 relay:** 4 (4) A/250 VAC, SPDT;

**Out2, 3 relay:** 2 (1) A/250 VAC, SPST NA (\*);

**Out1, 2, 3 SSR:** 10 VDC/15 mA;

**Linear Out:** 0/4... 20 mA, 0/2... 10 V;

**Out4 SSR:** 12 VDC/20 mA.

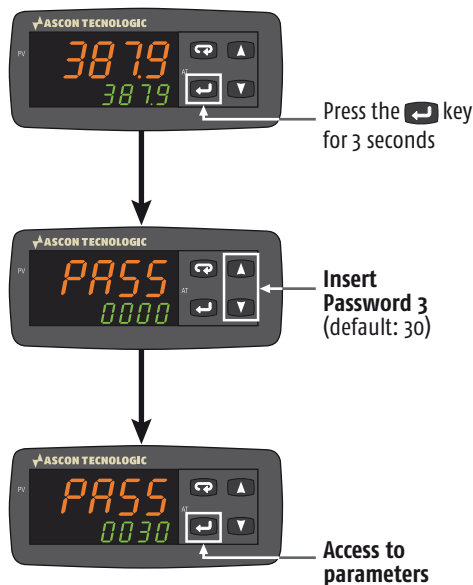
\* For servodrive models both **Out2** and **Out3** are to be selected as "M" in Configuration code; **Out2**: opens the valve, **Out3**: closes the valve.

### General notes about wiring

1. Safety regulations require a line switch marked as instrument disconnecting device. This switch must be easily reachable by the operator;
2. Do not run input wires together with power cables;
3. External components (like zener barriers, etc.) connected between sensor and input terminals may cause errors in measurement due to excessive and/or not balanced line resistance or possible leakage currents;
4. When a shielded cable is used, it should be connected at one point only;
5. Pay attention to the line resistance, a high line resistance may cause measurement errors.
6. To avoid electrical shocks, connect power line at last;
7. Before connecting the instrument to the power line, make sure that line voltage is equal to the voltage shown on the identification label;
8. The power supply input is NOT fuse protected. Please, provide an external fuse T type 1A, 250 V.

## 3. CONFIGURATION PROCEDURES

### Setting the parameters



Key	Editing Mode
	When the upper display shows a group (the lower is blank), this key allows to enter the selected group. When the upper display shows a parameter name and the lower display the value, this key allows to store value set and access the next parameter within the same group.
	Increase the displayed value or select the next element
	Decrease the displayed value or select the previous element
	A short pression on the button exits from the current parameter group and selects a new parameter group. A long pression allows to close the configuration parameter procedure (the instrument returns to the "Standard display").

### How to exit the "Configuration mode"

To exit from the Configuration mode, press the key for 3 seconds.

## 4. LIST OF THE PARAMETERS (PASS: 30)

### inP Group - Main and auxiliary input configuration

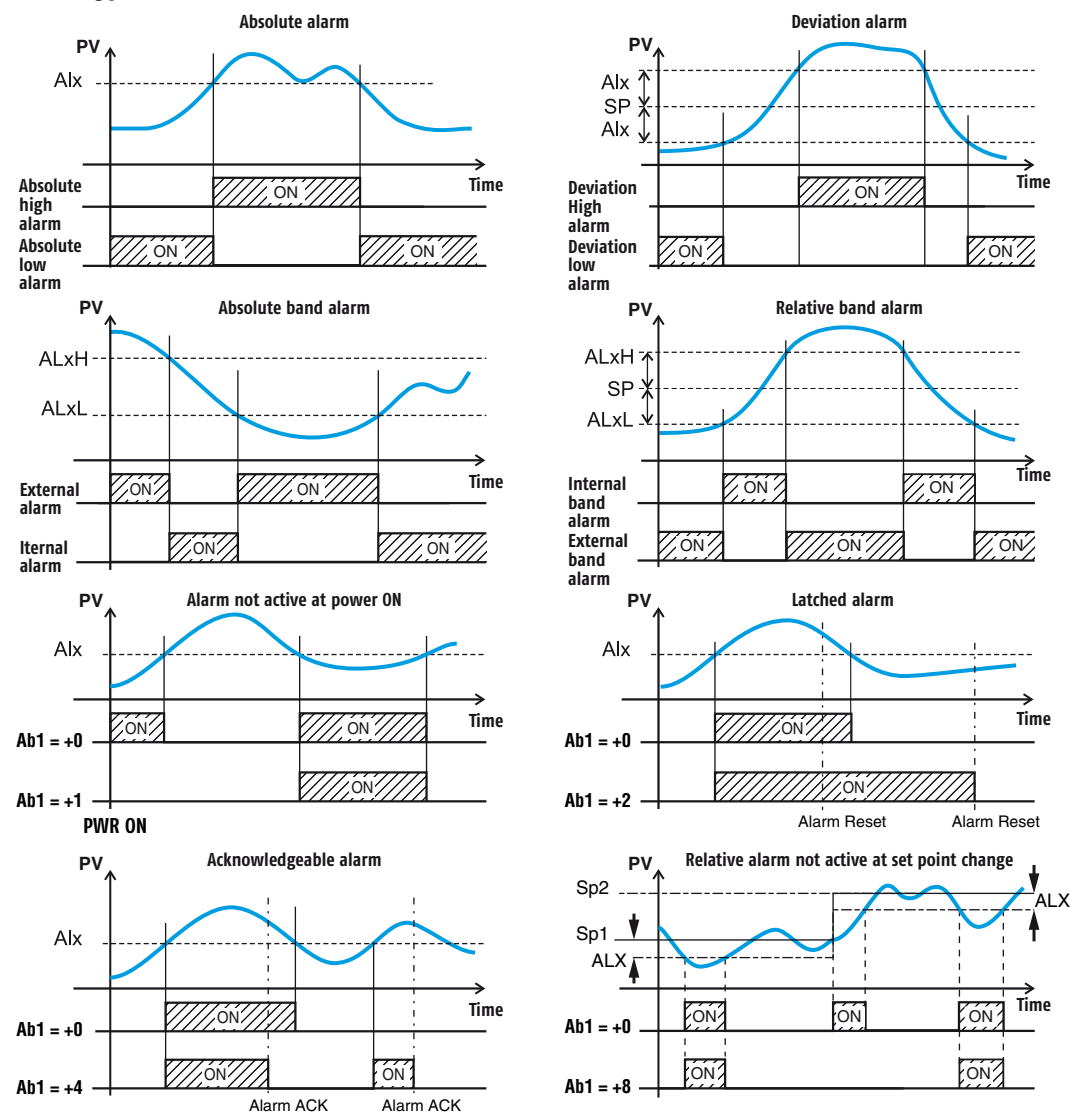
no.	Par.	Description	Dec.	Values	Default	Notes
1	SEnS	Model C		J = TC J (0... 1000°C/32... 1832°F); crAL = TC K (0... 1370°C/32... 2498°F); S = TC S (0... 1760°C/32... 3200°F); r = TC R (0... 1760°C/32... 3200°F); t = TC T (0... 400°C/32... 752°F); n = TC N (0... 1000°C/32... 1832°F); ir.J = Exergen IRS J (0... 1000°C/32... 1832°F); ir.cA = Exergen IRS K (0... 1370°C/32... 2498°F); Pt1 = RTD Pt 100 (-200... 850°C/-328... 1562°F); Pt10 = RTD Pt 1000 (-200... 500°C/-328... 932°F); 0.60 = 0... 60 mV; 12.60 = 12... 60 mV; 0.20 = 0... 20 mA; 4.20 = 4... 20 mA; 0.5 = 0... 5 V; 1.5 = 1... 5 V; 0.10 = 0... 10 V; 2.10 = 2... 10 V.		
		Model E		J = TC J (0... 1000°C/32... 1832°F); crAL = TC K (0... 1370°C/32... 2498°F); S = TC S (0... 1760°C/32... 3200°F); r = TC R (0... 1760°C/32... 3200°F); t = TC T (0... 400°C/32... 752°F); n = TC N (0... 1000°C/32... 1832°F); ir.J = Exergen IRS J (0... 1000°C/32... 1832°F); ir.cA = Exergen IRS K (0... 1370°C/32... 2498°F); Ptc = PTC (-55... 150°C/-67... 302°F); ntc = NTC (-50... 110°C/-58... 230°F); 0.60 = 0... 60 mV; 12.60 = 12... 60 mV; 0.20 = 0... 20 mA; 4.20 = 4... 20 mA; 0.5 = 0... 5 V; 1.5 = 1... 5 V; 0.10 = 0... 10 V; 2.10 = 2... 10 V.		
2	dp	Decimal Point Position (linear inputs) Decimal Point Position (non linear inputs)	0	0... 3 0/1	0	
3	SSC	Initial scale read-out for linear inputs	dp	-1999... 9999	0	
4	FSc	Full Scale Readout for linear inputs	dp	-1999... 9999	1000	
5	unit	Engineer unit		°C/°F	°C	
6	Fil	Digital filter on the measured value	1	0 (= OFF); 0.1... 20.0 s	1.0	
7	inE	Sensor error used to enable the safety output value		or = Over range; ur = Under range; our = Over and under range.	our	
8	oPE	Safety output value (% of the output)		-100... 100	0	
9	IO4.F	I/O 4 function		on = Output used as PWS for TX; out4 = Output 4 (digital output 4); dG2c = Digital input 2 driven by contact; dG2U = Digital input 2 driven by voltage.	out4	
10	diF1	Digital Input 1 function		oFF = Not used; 1 = Alarm reset; 2 = Alarm acknowledge (ACK); 3 = Hold of the measured value; 4 = Stand by mode; 5 = Manual mode; 6 = Program Start (on transition); 7 = Program Reset (on transition); 8 = Program Hold (on transition); 9 = Program Run/Hold; 10 = Program Run/Reset; 11 = SP1 - SP2 selection; 12 = SP1... SP4 binary selection; 13 = Digital inputs in parallel to  /  keys.	oFF	
11	diF2	Digital Input 2 function			oFF	
12	di.A	Digital Inputs Action (DI2 only if configured)		0 = DI1 direct action, DI2 direct action; 1 = DI1 reverse action, DI2 direct action; 2 = DI1 direct action, DI2 reverse action; 3 = DI1 reverse action, DI2 reverse action.	0	

### Out group - Output parameters

no.	Par.	Description	Dec.	Values	Default	Notes
13	o1t	Output 1 type (when Out 1 is a linear output)		0-20 = 0... 20 mA; 4-20 = 4... 20 mA; 0-10 = 0... 10 V; 2-10 = 2... 10 V.	0-20	
14	o1F	Out 1 function (when Out 1 is a linear output)	0	NonE = Output not used; H.rEG = Heating output; c.rEG = Cooling output; r.inP = Measure retransmission; r.Err = Error (SP - PV) retransmission; r.SP = Set point retransmission; r.SEr = Serial value retransmission.		
		Out 1 function (when Out 1 is a digital output)	0	NonE = Output not used; H.rEG = Heating output; c.rEG = Cooling output; AL = Alarm output; P.End = Program end indicator; P.Hld = Program hold indicator; P.uit = Program wait indicator; P.run = Program run indicator; P.Et1 = Program Event 1; P.Et2 = Program Event 2; or.bo = Out of range or burn out indicator; P.FAL = Power failure indicator; bo.PF = Out of range/burn out/Power failure indicator; St.by = Stand by status indicator; diF.1 = The output repeats the digital input 1 status; diF.2 = The output repeats the digital input 2 status; on = Out 1 always ON; riSP = Inspection request.	H.rEG	
15	Ao1L	Initial scale for the analog retransmission	dP	-1999... Ao1H	-1999	
16	Ao1H	Full scale for the analog retransmission	dP	Ao1L... 9999	9999	
17	o1AL	Alarms linked up with the out 1	0	0... 63; +1 = Alarm 1; +2 = Alarm 2; +4 = Alarm 3; +8 = Loop break alarm; +16 = Sensor Break (burn out); +32 = Overload on output 4.	1	
18	o1Ac	Out 1 action	0	dir = Direct action; rEU = Reverse action; dir.r = Direct with reversed LED; ReU.r = Reverse with reversed LED.	dir	
19	o2F	Out 2 function	0	See O1F - Out 1 function (digital output)	AL	
20	o2AL	Alarms linked up with the out 2	0	See O1AL - Alarms linked up with the out 1	1	
21	o2Ac	Out 2 action	0	See O1Ac - Out 1 action	dir	
22	o3F	Out 3 function	0	See O1F - Out 1 function (digital output)	AL	
23	o3AL	Alarms linked up with the out 3	0	See O1AL - Alarms linked up with the out 1	2	
24	o3Ac	Out 3 action	0	See O1Ac - Out 1 action	dir	
25	o4F	Out 4 function	0	See O1F - Out 1 function (digital output)	AL	
26	o4AL	Alarms linked up with the out 4	0	See O1AL - Alarms linked up with the out 1	AL1 + AL2	
27	o4Ac	Out 4 action	0	See O1Ac - Out 1 action	dir	

Note: When a servomotor control is desired, both **Out2** and **Out3** are to be selected as Heating or Cooling (o2F = o3F = H.rEG or o2F = o3F = c.rEG). Parameter [56] cont must be set as 3PE.

## Alarm types



## AL1 Group - Alarm 1 parameters

no.	Par.	Description	Dec.	Values	Default	Notes
28	AL1t	Alarm 1 type	0	nonE = Alarm not used; LoAb = Absolute low alarm; HiAb = Absolute high alarm; LHAo = Windows alarm in alarm outside the windows; LHAi = Windows alarm in alarm inside the windows; SE.br = Sensor Break; LodE = Deviation low alarm (relative); HidE = Deviation high alarm (relative); LHdo = Relative band alarm in alarm out of the band; LHdi = Relative band alarm in alarm inside the band.	HiAb	
29	Ab1	Alarm 1 function	0	0... 15: +1 = Not active at power up; +2 = Latched alarm (manual reset); +4 = Acknowledgeable alarm; +8 = Relative alarm not active at set point change.	0	
30	AL1L	- For High/low alarm, AL1 low limit; - For band alarm, AL1 low alarm	dp	From -1999 to AL1H (E.U.)	-1999	
31	AL1H	- For High/low alarm, AL1 high limit; - For band alarm, AL1 high alarm	dp	From AL1L to 9999 (E.U.)	9999	
32	AL1	AL1 threshold	dp	From AL1L to AL1H (E.U.)	0	
33	HAL1	AL1 hysteresis	dp	1... 9999 (E.U.)	1	
34	AL1d	AL1 delay	0	From 0 (oFF) to 9999 (s)	oFF	
35	AL1o	Alarm 1 enabling during Stand-by mode and out of range conditions	0	0 = Alarm 1 disabled during Stand-by and out of range; 1 = Alarm 1 enabled in stand by mode; 2 = Alarm 1 enabled in out of range condition; 3 = Alarm 1 enabled in stand by and overrange.	0	

## AL2 Group - Alarm 2 parameters

no.	Par.	Description	Dec.	Values	Default	Notes
36	AL2t	Alarm 2 type	0	See AL1t	LoAb	
37	Ab2	Alarm 2 function	0	See Ab1	0	
38	AL2L	- For High/low alarm, AL2 low limit; - For band alarm, AL2 low alarm	dp	See AL1L	-1999	
39	AL2H	- For High/low alarm, AL2 high limit; - For band alarm, AL2 high alarm	dp	See AL1H	9999	
40	AL2	AL2 threshold	dp	See AL1	0	
41	HAL2	AL2 hysteresis	dp	See HAL1	1	
42	AL2d	AL2 delay	0	See AL1d	oFF	
43	AL2o	Alarm 2 enabling during Stand-by mode and out of range conditions	0	See AL1o	0	

## AL3 Group - Alarm 3 parameters

no.	Par.	Description	Dec.	Values	Default	Notes
44	AL3t	Alarm 3 type	0	See AL1t	nonE	
45	Ab3	Alarm 3 function	0	See Ab1	0	
46	AL3L	- For High/low alarm, AL3 low limit; - For band alarm, AL3 low alarm	dp	See AL1L	-1999	
47	AL3H	- For High/low alarm, AL3 high limit; - For band alarm, AL3 high alarm	dp	See AL1H	9999	
48	AL3	AL3 threshold	dp	See AL1	0	
49	HAL3	AL3 hysteresis	dp	See HAL1	1	
50	AL3d	AL3 delay	0	See AL1d	oFF	
51	AL3o	Alarm 3 enabling during Stand-by mode and out of range conditions	0	See AL1o	0	

## LBA Group - Loop break alarm

no.	Par.	Description	Dec.	Values	Default	Notes
52	LbAt	LBA time	0	From 0 (oFF) to 9999 (s)	oFF	
53	LbSt	Delta measure used by LBA during Soft start	dp	From 0 (oFF) to 9999 (E.U.)	10	
54	LbAS	Delta measure used by LBA	dp	1... 9999 (E.U.)	20	
55	LbcA	Condition for LBA enabling	0	uP = Active when Pout = 100%; dn = Active when Pout = -100%; both = Active in both cases.	both	

## rEG Group - Control parameters

no.	Par.	Description	Dec.	Values	Default	Notes
56	cont	Control type	0	Pid = PID (heat and/or); On.FA = ON/OFF asymmetric hysteresis; On.FS = ON/OFF symmetric hysteresis; nr = Heat/Cool ON/OFF control with neutral zone; 3Pt = Servomotor control (when Out2 and Out3 have been ordered with code "M").	Pid	
57	Auto	Autotuning selection	0	-4 = Oscillating auto-tune with auto-restart at power ON and after all point change; -3 = Oscillating auto-tune with manual start; -2 = Oscillating tune with auto-start at first power ON only; -1 = Oscillating auto-tune with auto-restart at all power ON; 0 = Not used; 1 = Fast auto tuning with auto-restart at all power ON; 2 = Fast auto-tune with auto-start at first power ON only; 3 = FAST auto-tune with manual start; 4 = FAST auto-tune with automatic restart at power ON and after a set point change; 5 = Evo-tune with auto-restart at all power ON; 6 = Evo-tune with auto-start at first power ON only; 7 = Evo-tune with manual start; 8 = Evo-tune with auto-restart at power ON and after a set point change.	7	
58	Aut.r	Manual start of the Autotuning	0	oFF = Not active; on = Active.	oFF	
59	HSEt	Hysteresis of the ON/OFF control	dp	0... 9999 (E.U.)	1	
60	Pb	Proportional band	dp	1... 9999 (E.U.)	50	
61	ti	Integral time	0	From 0 (oFF) to 9999 (s)	200	
62	td	Derivative time	0	From 0 (oFF) to 9999 (s)	50	
63	Fuoc	Fuzzy overshoot control	2	0.00... 2.00	0.50	
64	tcH	Heating output cycle time	1	0.1... 130.0 (s)	20.0	
65	rcG	Power ratio between heating and cooling action	2	0.01... 99.99	1.00	
66	tcc	Cooling output cycle time	1	0.1... 130.0 (s)	20.0	
67	rS	Manual reset (Integral pre-load)	1	-100.0... +100.0 (%)	0.0	
68	Str.t	Servomotor stroke time	0	5... 1000 seconds	60	
69	db.S	Servomotor dead band	0	0... 100%	50	
70	od	Delay at power up	2	From 0.00 (oFF) to 99.59 (hh.mm)	oFF	
71	St.P	Maximum power output used during soft start	0	-100... 100 (%)	0	
72	SSt	Soft start time	2	0.00 (oFF); 0.01... 7.59 (hh.mm); inF (always ON).	oFF	
73	SS.th	Threshold for soft start disabling	dp	-1999... +9999 (E.U.)	9999	

## SP Group - Set point parameters

no.	Par.	Description	Dec.	Values	Default	Notes
74	nSP	Number of used set points	0	1... 4	1	
75	SPLL	Minimum set point value	dp	From -1999 to SPHL	-1999	
76	SPHL	Maximum set point value	dp	From SPLL to 9999	9999	
77	SP	Set point 1	dp	From SPLL to SPLH	0	
78	SP 2	Set point 2	dp	From SPLL to SPLH	0	
79	SP 3	Set point 3	dp	From SPLL to SPLH	0	
80	SP 4	Set point 4	dp	From SPLL to SPLH	0	
81	A.SP	Selection of the active set point	0	From 1 (SP 1) to nSP	1	
82	SP.rt	Remote set point type	0	RSP = The value coming from serial link is used as remote set point; trin = The value will be added to the local set point selected by A.SP and the sum becomes the operative set point; PErc = The value will be scaled on the input range and this value will be used as remote SP.	trin	
83	SPLr	Local/remote set point selection	0	loc = Local; rEn = Remote.	loc	
84	SP.u	Rate of rise for POSITIVE set point change (ramp UP)	2	0.01... 99.99 (inF) engineering units per minute	inF	
85	SP.d	Rate of rise for NEGATIVE set point change (ramp DOWN)	2	0.01... 99.99 (inF) engineering units per minute	inF	

## PAn Group - Operator HMI

no.	Par.	Description	Dec.	Values	Default	Notes
86	PAS2	Level 2 password (limited access level)	0	oFF (Level 2 not protected by password); 1... 200.	20	
87	PAS3	Level 3 password (complete configuration)	0	3... 200	30	
88	uSrb	button function during RUN TIME		nonE = No function; tunE = Auto-tune/self-tune enabling. A single press (longer than 1 second) starts the auto-tune; oPLo = Manual mode. The first pressure puts the instrument in manual mode (oPLo) while a second one puts the instrument in Auto mode; AAC = Alarm reset; ASI = Alarm acknowledge; chSP = Sequential set point selection; St.by = Stand by mode. The first press puts the instrument in stand by mode while a second one puts the instrument in Auto mode; P.run = Program run; P.rES = Program reset; P.r.H.r = Program run/hold/reset.	tunE	
89	diSP	Display management		nonE = Standard display; Pou = Power output; SPF = Final set point; Spo = Operative set point; AL1 = Alarm 1 threshold; AL2 = Alarm 2 threshold; AL3 = Alarm 3 threshold; Pr.tu = - During a soak, the instrument shows the soak elapsed time; - During a ramp the display shows the operative set point. At program end, the instrument alternately displays PEnd and the measured value; - When no program is running, the instrument shows the standard display; Pr.td = - During a soak, the instrument shows the soak remaining time (count down); - During a ramp the display shows the operative set point. At program end, the instrument alternately displays PEnd and the measured value; - When no program is running, the instrument shows the standard display; P.t.tu = When the programmer is running, the display shows the total elapsed time. At program end, the instrument alternately displays PEnd and the measured value; P.t.td = When the programmer is running, the display shows the total remaining time (count down). At program end, the instrument alternately displays PEnd and the measured value; PErc = Percent of the power output used during soft start (when the soft start time is equal to infinite, the limit is always active and it can also be used when ON/OFF control is selected); PoS = Valve position (servomotor control).	0	
90	di.cl	Display colour		0 = The display colour shows the actual deviation (PV - SP); 1 = Display red (fix); 2 = Display green (fix); 3 = Display orange (fix).	0	



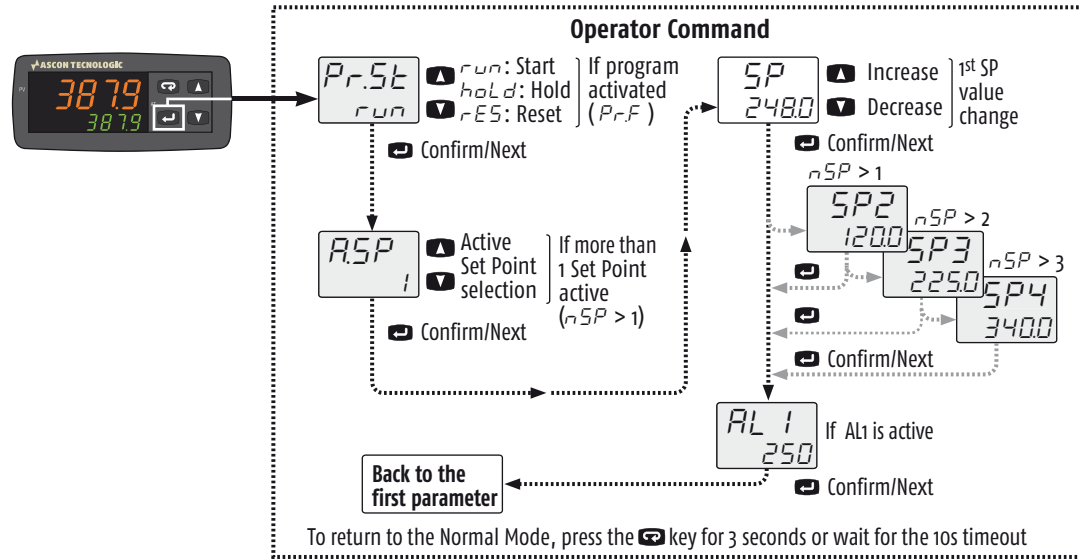


## 5. OPERATIVE MODES

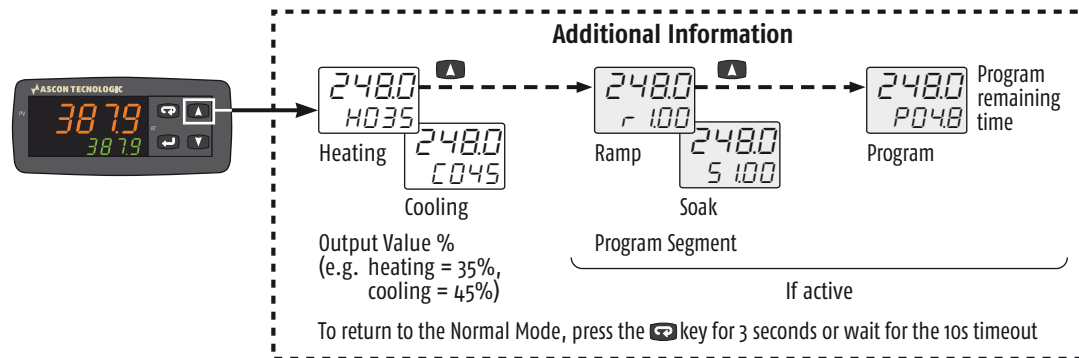
### Keyboard function when the instrument is in Auto mode

Key	Operator Mode
	Access to: - Operator Commands (Setpoint selection ...) - Parameters - Configuration
	Access to Operator additional information (Output value, program running time ...)
	Set Point Access
	Start programmed function with <i>uSrb</i> parameter (Autotune, Auto/Man, Program Run/Hold/Reset ...)

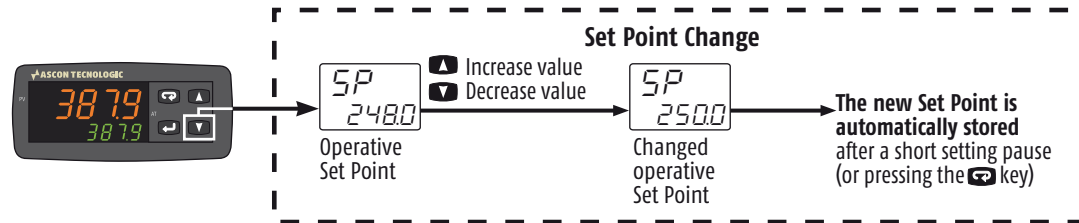
### Operator Commands



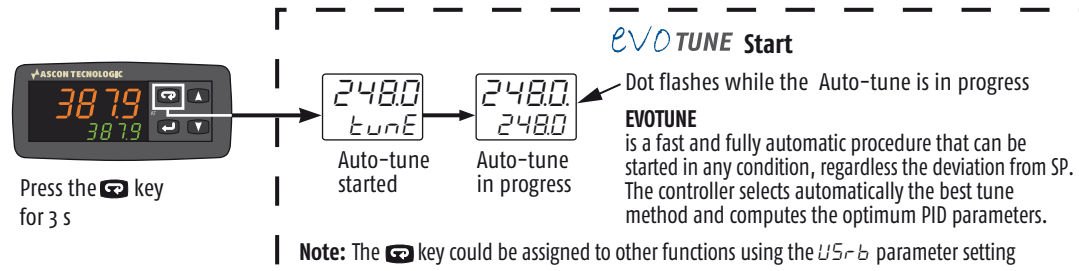
### Additional information



### Set Point Change



### Running the Tuning functions



## 6. ERROR MESSAGES

### Out of range signals

The instrument points out, on the upper display, the OVER-RANGE and UNDER-RANGE conditions using the following indications:

Over-range: 0000  
 Under-range: U.U.U.U.

The sensor break will be signalled as an out of range: - - - -

**Note:** When an over-range or an under-range is detected, the alarms operate as in presence of the maximum or the minimum measurable value respectively.

To check the out of span Error condition, proceed as follows:

1. Check the input signal source and the connecting line.
2. Make sure that the input signal is in accordance with the instrument configuration. Otherwise, modify the input configuration (see section 4).
3. If no error is detected, send the instrument to your supplier to be checked.

### List of possible errors

- ErAt** Fast Auto-tune cannot start. The measure value is too close to the set point. Push the button in order to delete the error message.
- ould** Overload on output 4. The message shows that a short circuit is present on Out 4 when it is used as output or transmitter power supply. When the short circuit disappears the output restarts to operate.
- NoAt** Auto-tune not finished within 12 hours.
- ErEP** Possible problem in the instrument memory. The message should automatically disappear, if the error persists, send the instrument to your supplier.
- RonE** Possible problem of the firmware memory. If this error is detected, send the instrument to your supplier.
- ErRt** Possible problem of the calibration memory. If this error is detected, send the instrument to your supplier.

## 7. GENERAL NOTES

### Proper use

Every possible use not described in this manual must be consider as a improper use.

This instrument is in compliance with EN 61010-1 "Safety requirements for electrical equipment for measurement, control and laboratory use"; for this reason it could not be used as a safety equipment.

**Whenever a failure or a malfunction of the control device may cause dangerous situations for persons, thing or animals, please remember that the plant has to be equipped with additional safety devices.**

Ascon Tecnologic S.r.l. and its legal representatives do not assume any responsibility for any damage to people, things or animals deriving from violation, wrong or improper use or in any case not in compliance with the instrument's features.

### Declaration of conformity and Manual retrieval

KR5 is a panel mounting, Class II instrument. It has been designed with compliance to the European Directives.

All information about the controller use can be found in the **Engineering Manual**:

**ISTR-MKR5-ENGOx** ("x" is the revision).

The Declaration of Conformity and the manual of the controller can be downloaded (free of charge) from the web-site:

[www.ascontecnologic.com](http://www.ascontecnologic.com)

Once connected to the web-site, search:

**KR5**

then click on **KR5**.

In the lower part of the product page (in any language) is present the download area with links to the documents available for the controller (in the available languages).

### Maintenance

This instrument does not requires periodical recalibration and it have no consumable parts so that no particular maintenance is required.

Sometimes it is advisable to clean the instrument.

1. SWITCH THE EQUIPMENT OFF (power supply, relay output, etc.).
2. Using a vacuum cleaner or a compressed air jet (max. 3 kg/cm<sup>2</sup>) remove all deposits of dust and dirt which may be present on the case and on the internal circuits being careful not to damage the electronic components.
3. To clean external plastic or rubber parts use only a cloth moistened with:
  - Ethyl Alcohol (pure or denatured) [C<sub>2</sub>H<sub>5</sub>OH] or
  - Isopropyl Alcohol (pure or denatured) [(CH<sub>3</sub>)<sub>2</sub>CHOH] or
  - Water (H<sub>2</sub>O).
4. Make sure that there are no loose terminals.
5. Before turning ON the instrument make sure it is perfectly dry.
6. Apply the power supply to the instrument.

### Warranty

This product is under warranty against manufacturing defects or faulty materials that are found within 18 months from delivery date. The warranty is limited to repairs or to the replacement of the instrument.

The tampering of the instrument or an improper use of the product will bring about the immediate withdrawal of the warranty effects.

In the event of a faulty instrument, either within the period of warranty, or further to its expiry, please contact our sales department to obtain authorisation for sending the instrument to our company.

The faulty product must be shipped to Ascon Tecnologic with a detailed description of the faults found, without any fees or charge for Ascon Tecnologic, except in the event of alternative agreements.

## 8. ORDER CODE

Model: KR5 A B C D E F G H I

Line KM 5

Optional functions A

Controller + programmer + Setpoint setter P

Power Supply B

100... 240Vac (-15... +10%) H

24Vac (-25... +12%) or 24Vdc (-15... +25%) L

Input C

TC, PT100, PT1000, mA, mV, V + Digital Input 1 C

TC, NTC, PTC, mA, mV, V + Digital Input 1 E

Output OP1	D
Isolated Analogue Output (0/4... 20 mA, 0/2... 10 V)	I
Relay (1 SPDT, 4 A/250 Vac)	R
VDC for SSR (12 Vdc/20 mA)	O

Output OP2	E
None	-
Relay (1 SPST NO, 2 A/250 Vac)	R
VDC for SSR VDC (12 Vdc/20 mA)	O
Servomotor drive Relay (1 SPST NO, 2 A/250 Vac)	M

Output OP3	F
None	-
Relay (1 SPST NO, 2 A/250 Vac)	R
VDC for SSR VDC (12 Vdc/20 mA)	O
Servomotor drive Relay (1 SPST NO, 2 A/250 Vac)	M

Output OP4	G
Digital I/O (see the Electrical Connections paragraph for details)	D

Serial Communications	H
TTL	-
RS485 Modbus	S

Terminal Type	I
Standard (screw type non removable terminal blocks)	-
With plug-in screw type terminal blocks	E
With plug-in clamp type terminal blocks	M
With plug-in terminal blocks (fixed part only)	N

**Note:** For servomotor drive, both Output 2 and Output 3 codes must be selected as "M".