Rotary Servomotors SGMAV



Model Designations

Without Gears

....

SGMAV

01

Α

D

Α

2

1 7th

 Σ -V Series Servomotor SGMAV 1st+2nd digits 3rd digit

4 di 5th digit 6th digit

7th digit

1st+2nd digits Rated Output

Code		Specifications
A5	50 W	
01	100 W	
C2	150 W	
02	200 W	
04	400 W	
06	550 W	
08	750 W	
10	1.0 kW	1

5th digit Design Revision Order

Code	Specifications
Α	Standard

6th digit Shaft End

Code	Specifications			
2 Straight without key (standard				
6	Straight with key and tap (optional)			
В	With two flat seats (optional)			

7th digit Options

Code	Specifications
1	Without options
С	With holding brake (24 VDC)
E	With oil seal and holding brake (24 VDC)
S	With oil seal

3rd digit Power Supply Voltage

Code	Specifications
Α	200 VAC

4th digit Serial Encoder

Code	Specifications
3	20-bit absolute (standard)
D	20-bit incremental (standard)

Features

- Super high power rate (Extremely low inertia)
- Instantaneous peak torque (300% of rated torque)
- Mounted high-resolution serial encoder: 20 bits
- Maximum speed: 6,000 min⁻¹
- Wide selection: 50 W to 1.0 kW capacity, holding brake options

Application Examples

- Semiconductor equipment
- Chip mounters
- PCB drilling stations
- Robots
- Material handling machines
- Food processing equipment



Model	SGMAV-10ADA61	SGMAV-06ADA61	SGMAV-01ADA61
Rated Output	1.0 kW	550 W	100 W
Flange Face	80 mm x 80 mm	60 mm x 60 mm	40 mm x 40 mm

Ratings and Specifications

Time Rating: Continuous Vibration Class: V15

Insulation Resistance: 500 VDC, 10 $\mbox{M}\Omega$ min.

Ambient Temperature: 0 to 40°C **Excitation:** Permanent magnet Mounting: Flange-mounted Thermal Class: B

Withstand Voltage: 1500 VAC for one minute Enclosure: Totally enclosed, self-cooled, IP65

(except for shaft opening)

Ambient Humidity: 20% to 80% (no condensation)

Drive Method: Direct drive

Rotation Direction: Counterclockwise (CCW) with forward run

reference when viewed from the load side

Voltage	Voltage			230 V						
Servomotor Model: SGMAV-		A5A	01A	C2A	02A	04A	06A	08A	10A	
Rated Output*1	W	50	100	150	200	400	550	750	1000	
Rated Torque*1, *2	Nm	0.159	0.318	0.477	0.637	1.27	1.75	2.39	3.18	
Instantaneous Peak Torque*1	Nm	0.477	0.955	1.43	1.91	3.82	5.25	7.16	9.55	
Rated Current*1	Arms	0.66	0.91	1.3	1.5	2.6	3.8	5.3	7.4	
Instantaneous Max. Current ¹	Arms	2.1	2.8	4.2	5.3	8.5	12.2	16.6	23.9	
Rated Speed*1	min ⁻¹	3000								
Max. Speed ⁻¹	min ⁻¹				60	00				
Torque Constant	Nm/Arms	0.265	0.375	0.381	0.450	0.539	0.496	0.487	0.467	
Rotor Moment of Inertia	×10 ⁻⁴ kgm ²	0.0242 (0.0389)	0.0380 (0.0527)	0.0531 (0.0678)	0.116 (0.180)	0.190 (0.254)	0.326 (0.403)	0.769 (0.940)	1.20 (1.41)	
Rated Power Rate ¹	kW/s	10.4	26.6	42.8	35.0	84.9	93.9	74.1	84.3	
Rated Angular Acceleration*1	rad/s ²	65800	83800	89900	54900	67000	53700	31000	26500	
Applicable SERVOPACK	SGDV-	R70	R90	1R	6A	2R8	5R5A	5R5A	120A	

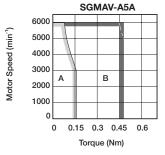
These items and torque-speed characteristics quoted in combination with an SGDV SERVOPACK are at an armature winding temperature of 100°C. Other *1: values quoted are at 20°C.

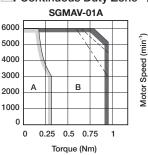
SGMAV-C2A, -02A, -04A, -06A, -08A: 250 mm \times 250 mm \times 6 mm SGMAV-10A: 300 mm × 300 mm × 12 mm

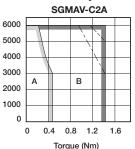
Note: The values in parentheses are for servomotors with holding brakes.

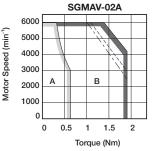
Motor Speed (min⁻¹)

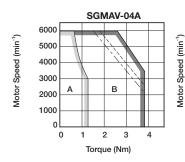
● Torque-Speed Characteristics A: Continuous Duty Zone B: Intermittent Duty Zone

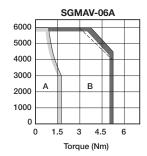


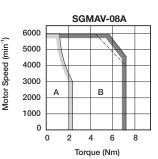


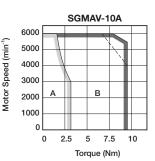












The characteristics of the intermittent duty zone differ depending on the supply voltages. The solid, dotted, and dashed-dotted lines of the intermittent duty zone indicate the characteristics when a servomotor runs with the following combinations:

- The solid line: With a three-phase 200 V or a single-phase 230 V SERVOPACK
- The dotted line: With a single-phase 200 V SERVOPACK
- The dashed-dotted line: With a single-phase 100 V SERVOPACK

An SGMAV-A5A servomotor combined with a single-phase 200 V SERVOPACK has the same characteristics as one combined with a three-phase 200 V

- 2 When the effective torque is within the rated torque, the servomotor can be used within the intermittent duty zone.
- 3 When the main circuit cable length exceeds 20 m, note that the intermittent duty zone of the Torque-Speed Characteristics will shrink as the line-to-line voltage

^{*2:} Rated torques are continuous allowable torque values at 40°C with an aluminum heat sink of the following dimensions attached. SGMAV-A5A, -01A: 200 mm \times 200 mm \times 6 mm

SGMAV

Ratings and Specifications

Derating Rate for Servomotor Fitted with an Oil Seal

When a motor is fitted with an oil seal, use the following derating rate because of the higher friction torque.

Servomotor Model SGMAV-	A5A	01A	C2A	02A	04A	06A	08A	10A
Derating Rate %	80	90		95				

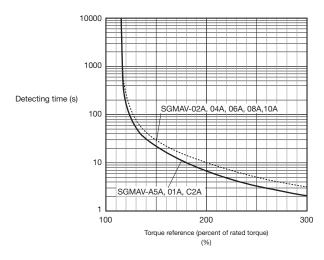
Holding Brake Electrical Specifications

Haldin v Duales		Servomotor Rated Output W	Holding Brake Specifications						
Holding Brake Rated Voltage			Capacity W	Holding Torque Nm	Coil Resistance Ω (at 20°C)	Rated Current A (at 20°C)	Brake Release Time ms	Brake Operation Time ms	
	SGMAV-A5A	50	5.5	0.159	103	0.23	60	100	
	SGMAV-01A	100	5.5	0.318	103	0.23	60	100	
	SGMAV-C2A	150	5.1	0.477	114	0.21	60	100	
24 VDC +10%	SGMAV-02A	200	6	0.637	97.4	0.25	60	100	
24 VDC _{-10%}	SGMAV-04A	400	0	1.27	97.4			100	
	SGMAV-06A	550	8	1.75	74.3	0.32	80	100	
	SGMAV-08A	750	6.5	2.39	87.7	0.27	80	100	
	SGMAV-10A	1000	7	3.18	82.8	0.29	80	100	

Notes: 1 The holding brake is only used to hold the load and cannot be used to stop the servomotor.

Overload Characteristics

The overload detection level is set under hot start conditions at a servomotor ambient temperature of 40°C.



Note: Overload characteristics shown above do not guarantee continuous duty of 100% or more output. Use a servomotor with effective torque within the continuous duty zone of Torque-Speed Characteristics.

² The holding brake open time and holding brake operation time vary depending on which discharge circuit is used. Make sure holding brake open time and holding brake operation time are correct for your servomotor.

³ A 24-VDC power supply is provided by customers.

Ratings and Specifications

Allowable Load Moment of Inertia at the Motor Shaft

The rotor moment of inertia ratio is the value for a servomotor without a gear and a brake.

Sei	rvomotor Model	Servomotor Rated Output	Allowable Load Moment of Inertia (Rotor Moment of Inertia Ratio)
	A5A, 01A, C2A, 02A	50 to 200 W	30 times
SGMAV-	04A, 06A, 08A	400 to 750 W	20 times
	10A	1000 W	10 times

Load Moment of Inertia

The larger the load moment of inertia, the worse the movement response.

The allowable load moment of inertia (J_L) depends on the motor capacity, as shown above. This value is provided strictly as a guideline and results may vary depending on servomotor drive conditions.

Use the AC servo drive capacity selection program SigmaJunmaSize+ to check the operation conditions. The program can be downloaded for free from our web site (http://www.yaskawa.eu.com).

An overvoltage alarm (A.400) is likely to occur during deceleration if the load moment of inertia exceeds the allowable load moment of inertia. SERVOPACKs with a built-in regenerative resistor may generate a regenerative overload alarm (A.320). Take one of the following steps if this occurs.

- Reduce the torque limit.
- Reduce the deceleration rate.
- · Reduce the maximum speed.
- Install an external regenerative resistor if the alarm cannot be cleared using the steps above. Refer to Regenerative Resistors on page 364.

Regenerative resistors are not built into SERVOPACKs for 400 W motors or less.

External regenerative resistors are required when this condition is exceeded or if the allowable loss capacity (W) of the built-in regenerative resistor is exceeded due to regenerative drive conditions when a regenerative resistor is already built in.

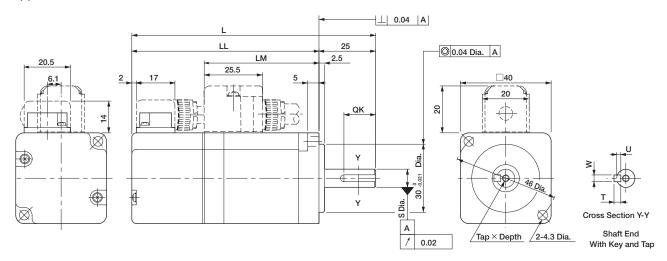
Allowable Radial and Thrust Loads

Design the mechanical system so thrust and radial loads applied to the servomotor shaft end during operation fall within the ranges shown in the table.

Servomotor	Servomotor Model		Allowable Thrust Load (Fs) N	LF mm	Reference Diagram
	A5A				
	01A	78	54	20	< LF →
	C2A				
SGMAV-	02A				
SGIVIAV-	04A	245	74	25	Fs Fs
	06A				
	08A	392	147	35	
	10A	392	147	35	

External Dimensions Units: mm

(1) 50 to 150 W

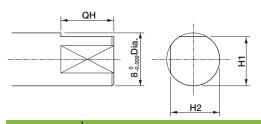


Model	L	LL	LM	s	T D .!!	Key Dimensions				Approx.	
SGMAV-	_	LL	LIVI		Tap × Depth	QK	U	W	Т	Mass kg	
A5A□A21 (A5A□A2C)	95.5	70.5	38.5	0 0 *	No tap		No	key		0.3	
A5A□A61 (A5A□A6C)	(140.5)	(115.5)	36.5	5 8 0 * -0.009	M3×6L	14	1.8	3	3	(0.6)	
01A A21 (01A A2C)	107.5	82.5	50.5	8 8 -0.009	No tap			0.4			
01A□A61 (01A□A6C)	(152.5)	(127.5)	50.5		M3×6L	14	1.8	3	3	(0.7)	
C2A□A21 (C2A□A2C)	119.5	94.5	60.5	0 0	No tap		No	key		0.5 (0.8)	
C2A□A61 (C2A□A6C)	(164.5)	(139.5)	62.5	62.5 8 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	M3×6L	14	1.8	3	3		

Note: The models and values in parentheses are for servomotors with holding brakes.

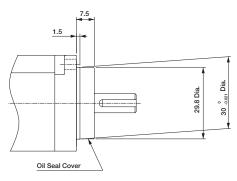
<Shaft End and Other Options>

With Two Flat Seats



Model	Dimensions of	Servomotor with Two Flat Seats				
SGMAV-	QH	H1	H2			
A5A AB						
01A□AB□	15	7.5	7.5			
C2A AB						

With an Oil Seal

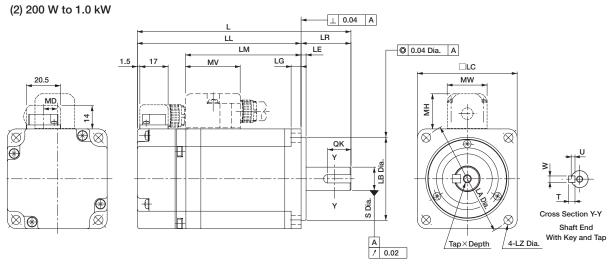


Note: The 7th digit of the model designation is "S" or "E."

The key dimensions are the same as those in the table above.

^{*:} When you need the same shaft diameter as the conventional servomotors, contact your Yaskawa representative.

External Dimensions Units: mm

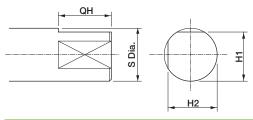


Model	L	LL	LM		FI	lange l	Face D	Dimens	sions		s	Тар ×	ŀ	Key Dim	ension	S	MD	MW	МН	MV	Approx.
SGMAV-		LL	LIVI	LR	LE	LG	LC	LA	LB	LZ	•	Depth	QK	U	W	Т	MD	IVIVV	IVIH	IVIV	Mass kg
02A□A21 (02A□A2C)	110	80	51	30	3	6	60	70	50 0	5.5	14_0.011	No tap		No	key		8.5	23.1	20.4	27,8	0.9
02A□A61 (02A□A6C)	(150)	(120)	31	30	3	b	60	70	5U _{-0.025}	5.5	14-0.011	M5×8L	14	3	5	5	0.5	23.1	20.4	21,0	(1.5)
04A□A21 (04A□A2C)	128.5	98.5	69.5	30	3	6	60	70	50 0	5.5	4.0	No tap		No	key		8.5	00.1	00.4	07.0	1.2
04A□A61 (04A□A6C)	(168.5)	(138.5)	69.5	30	3	б	60	70	50 _0.025	5.5	5 14-0.011	M5×8L	14	3	5	5	6.5	23.1	20.4	27,8	(1.8)
06A□A21 (06A□A2C)	154.5	124.5	05.5	30		•	00	70	50 0		0	No tap		No	key		0.5	00.4	00.4	07.0	1.7
06A□A61 (06A□A6C)	(200.5)	(170.5)	95.5	30	3	6	60	70	50 -0.025	5.5	14_0.011	M5×8L	14	3	5	5	8.5	23.1	20.4	27,8	(2.4)
08A□A21 (08A□A2C)	155	115	85				80	90	0	7	0 *	No tap		No	key		40.0	30			2.6
08A A61 (08A A6C)	(200)	(160)	85	40	3	8	80	90	70 -0.030	/	19-0.013	M6×10L	22	3.5	6	6	13.8	30	21.6	23,5	(3.2)
10A A21 (10A A2C)	185	145	445						0	_	40 ° *	No tap		No	key		40.0				3.6
10A A61 (10A A6C)	(235)	(195)	115	40	3	8	80	90	70 -0.030	7	19-0.013	M6×10L	22	3.5	6	6	13.8	30	21.6	23,5	(4.6)

Note: The models and values in parentheses are for servomotors with holding brakes.

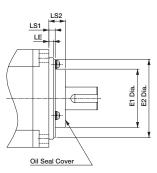
<Shaft End and Other Options>

With Two Flat Seats



Model	Dimensions of Servomotor with Two Flat Seats							
SGMAV-	QH	S	H1	H2				
02A□AB□								
04A□AB□	14	14_0.011	13	13				
06A□AB□	1							
08A□AB□	22	40.0	18	18				
10A□AB□	22	19 _0.013	18	18				

With an Oil Seal



Model	Dimensions of Servomotor with an Oil Seal						
SGMAV-	E1	E2	LS1	LS2			
02A, 04A, 06A	36	48	4	10			
08A,10A	49	66	6	11			

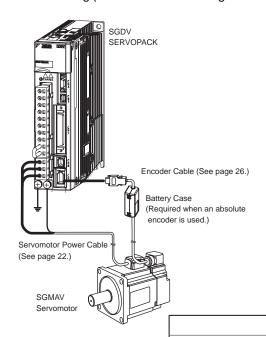
Note: The 7th digit of the model designation is "S" or "E."

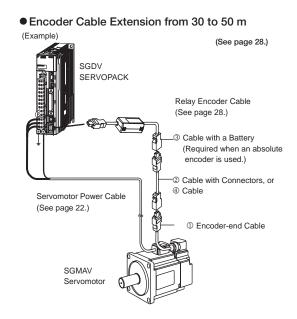
The key dimensions are the same as those in the table above.

^{*:} When you need the same shaft diameter as the conventional servomotors, contact your Yaskawa representative.

Cables Connections

• Standard Wiring (Max. encoder cable length: 20 m)





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- Separate the servomotor power cable wiring from the I/O signal cable and encoder cable at least 30 cm, and do not bundle or run them in the same duct.
- When the cable length exceeds 20 m, be sure to use a relay encoder cable.
- When the power cable length exceeds 20 m, note that the intermittent duty zone of the Torque-Speed Characteristics will shrink as the line-to-line voltage drops.

Servomotor Power Cable

Name	Servomotor	Longth	Orde	r No.	Specifications	Details	
Name	Rated Output	Length	Standard Type	Flexible Type	Specifications	Details	
		3 m	JZSP-CSM01-03-E-G#	JZSP-CSM21-03-E-G#		d	
		5 m	JZSP-CSM01-05-E-G#	JZSP-CSM21-05-E-G#			
	50 to 150 W	10 m	JZSP-CSM01-10-E-G#	JZSP-CSM21-10-E-G#			
		15 m	JZSP-CSM01-15-E-G#	JZSP-CSM21-15-E-G#			
		20 m	JZSP-CSM01-20-E-G#	JZSP-CSM21-20-E-G#			
		3 m	JZSP-CSM02-03-E-G#	JZSP-CSM22-03-E-G#	SERVOPACK end		
For Servomotor		5 m	JZSP-CSM02-05-E-G#	JZSP-CSM22-05-E-G#	Servomotor end ServorAck end		
without Holding	200 to 550 W	10 m	JZSP-CSM02-10-E-G#	JZSP-CSM22-10-E-G#		(1)	
Brakes		15 m	JZSP-CSM02-15-E-G#	JZSP-CSM22-15-E-G#			
		20 m	JZSP-CSM02-20-E-G#	JZSP-CSM22-20-E-G#			
		3 m	JZSP-CSM03-03-E-G#	JZSP-CSM23-03-E-G#			
	750 144	5 m	JZSP-CSM03-05-E-G#	JZSP-CSM23-05-E-G#			
	750 W, -	10 m	JZSP-CSM03-10-E-G#	JZSP-CSM23-10-E-G#			
		15 m	JZSP-CSM03-15-E-G#	JZSP-CSM23-15-E-G#			
		20 m	JZSP-CSM03-20-E-G#	JZSP-CSM23-20-E-G#			

Note: The digit "#" of the order number represents the design revision.

(Cont'd)

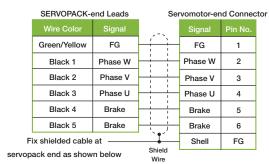
Name	Servomotor	Longth	Orde	er Nr.	Specifications	Details	
Name	Rated Output	Length	Standard Type	Flexible Type	Specifications	Details	
		3 m	JZSP-CSM11-03-E-G#	JZSP-CSM31-03-E-G#			
			5 m	JZSP-CSM11-05-E-G#	JZSP-CSM31-05-E-G#		
	50 to 150 W	10 m	JZSP-CSM11-10-E-G#	JZSP-CSM31-10-E-G#			
		15 m	JZSP-CSM11-15-E-G#	JZSP-CSM31-15-E-G#			
		20 m	JZSP-CSM11-20-E-G#	JZSP-CSM31-20-E-G#			
		3 m	JZSP-CSM12-03-E-G#	JZSP-CSM32-03-E-G#	Servomotor end SERVOPACK end		
For Servomotor		5 m	JZSP-CSM12-05-E-G#	JZSP-CSM32-05-E-G#			
with Holding 200 to	200 to 550 W	10 m	JZSP-CSM12-10-E-G#	JZSP-CSM32-10-E-G#		(2)	
Brakes		15 m	JZSP-CSM12-15-E-G#	JZSP-CSM32-15-E-G#			
		20 m	JZSP-CSM12-20-E-G#	JZSP-CSM32-20-E-G#			
	750 W, 1.0 kW	3 m	JZSP-CSM13-03-E-G#	JZSP-CSM33-03-E-G#			
		5 m	JZSP-CSM13-05-E-G#	JZSP-CSM33-05-E-G#			
		10 m	JZSP-CSM13-10-E-G#	JZSP-CSM33-10-E-G#			
		15 m	JZSP-CSM13-15-E-G#	JZSP-CSM33-15-E-G#			
		20 m	JZSP-CSM13-20-E-G#	JZSP-CSM33-20-E-G#			
	50 to 150 W		JZSP-CSM	//9-1-E-G1	Crimped Type (A crimp tool is required.)	(3)	
Servomotor-end Connector Kit	200 to 550 W		JZSP-CSM	//9-2-E-G1		(4)	
	750 W, 1.0 kW		JZSP-CSM	И9-3-E-G1		(5)	

Note: The digit "#" of the order number represents the design revision.

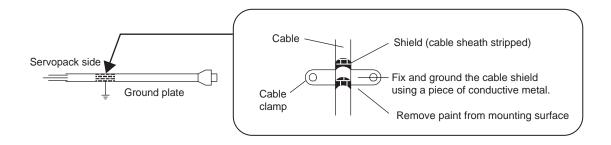
(1) Wiring Specifications for Servomotors without Holding Brakes

SERVOPACK-	end Leads	Se	Servomotor-end Connect				
Wire Color	Signal		Signal	Pin No.			
Green/Yellow	FG		FG	1			
Black 1	Phase W		Phase W	2			
Black 2	Phase V		Phase V	3			
Black 3	Phase U		Phase U	4			
			-	5			
			_	6			

(2) Wiring Specifications for Servomotor with Holding Brakes



Note: No polarity for connection to a holding brake.



SGMAV

Selecting Cables

(3) Servomotor-end Connector Kit Specifications: For 50 to 150 W Servomotors

Items	Specifications	External Dimensions mm
Order No.	JZSP-CSM9-1-E-G1 (Cables are not included.)	
Applicable Servomotors	SGMAV-A5A, -01A, -C2A	
Manufacturer	J.S.T. Mfg. Co., Ltd.	\$ * - * * - * * - * * - * * - * - * - * * * * * *
Receptacle Housing	J1FSN-06V-K (YE)	
Electrical Contact	SJ1F-01GF-P0.8	26.3
Applicable Wire Size	AWG20 to 24	
Outer Diameter of Insulating Sheath	1.11 dia. to 1.53 dia. mm	\$
Mounting Screw	M2 Pan-head screw	<u> </u>
Applicable Cable Outer Diameter	7±0.3 dia. mm	20.0

Note: A crimp tool (Model no.: YRS-8841) is required. Contact the respective manufacturer for more information.

(4) Servomotor-end Connector Kit Specifications: For 200 to 550 W Servomotors

Items	Specifications	External Dimensions mm
Order No.	JZSP-CSM9-2-E-G1 (Cables are not included.)	J2700M
Applicable Servomotors	SGMAV-02A, -04A, -06A	
Manufacturer	J.S.T. Mfg. Co., Ltd.	\$
Receptacle Housing	J2FSN-06V-K (YE)	
Electrical Contact	SJ2F-01GF-P1.0	28.6 8.3
Applicable Wire Size	AWG20 to 24	
Outer Diameter of Insulating Sheath	1.11 dia. to 1.53 dia. mm	\$
Mounting Screw	M2 Pan-head screw	
Applicable Cable Outer Diameter	7±0.3 dia. mm	23.1

 $Note: \ A\ crimp\ tool\ (Model\ no.:\ YRS-8861)\ is\ required.\ Contact\ the\ respective\ manufacturer\ for\ more\ information.$

(5) Servomotor-end Connector Kit Specifications: For 750 W, 1.0 kW Servomotors

Items	Specifications	External Dimensions mm
Order No.	JZSP-CSM9-3-E-G1 (Cables are not included.)	10
Applicable Servomotors	SGMAV-08A,-10A] J3700M
Manufacturer	J.S.T. Mfg. Co., Ltd.	g
Receptacle Housing	J3FSN-06V-K (YE)	• • • • • • • • • • • • • • • • •
Cable Type	Flexible	<u> </u>
Electrical Contact	SJ3F-01GF-P1.8	24.2 1 10.9 1
Applicable Wire Size	AWG16 to 24	
Outer Diameter of Insulating Sheath	1.53 dia. to 2.5 dia. mm	
Mounting Screw	M2.5 Pan-head screw] <u> </u>
Applicable Cable Outer Diameter	8±0.3 dia. mm	30.0 23.5

Note: The following crimp tools are required. For power terminals: Model no. YRF-880 For brake terminals: Model no. YRF-881

Contact the respective manufacturer for more information.

(6) Cable Specifications: For 50 to 550 W Servomotors

Items	Standard Type	Flexible Type		
Order No.	JZSP-CSM90-□□-E (50 m max.)	JZSP-CSM80-□□-E (50 m max.)		
Specifications	UL2517 (Rating temperature: 105°C) AWG20×6C For power line: AWG20 (0.52 mm²) Outer diameter of insulating sheath: 1.53 dia. mm For holding brake line: AWG20 (0.52 mm²) Outer diameter of insulating sheath: 1.53 dia. mm	UL2517 (Rating temperature: 105°C) AWG22×6C For power line: AWG22 (0.33 mm²) Outer diameter of insulating sheath: 1.37 dia. mm For holding brake line: AWG22 (0.33 mm²) Outer diameter of insulating sheath: 1.37 dia. mm		
Finished Dimensions	7±0.3 dia. mm			
Internal Configuration and Lead Color	(Green/ (yellow)	White Red		
Yaskawa Standard Specifications (Standard Length)	Cable length: 5 m, 10 m, 15 m, 20 m, 30 m, 40 m, 50 m			

(7) Cable Specifications: For 750 W, 1.0 kW Servomotors

Items	Standard Type	Flexible Type	
Order No.	JZSP-CSM91-□□-E (50 m max.)	JZSP-CSM81-□□-E (50 m max.)	
Specifications	UL2517 (Rating temperature: 105°C) AWG16×4C, AWG20×2C For power line: AWG16 (1.31 mm²) Outer diameter of insulating sheath: 2.15 dia. mm For holding brake line: AWG20 (0.52 mm²) Outer diameter of insulating sheath: 1.6 dia. mm	UL2517 (Rating temperature: 105°C) AWG16×4C, AWG22×2C For power line: AWG16 (1.31 mm²) Outer diameter of insulating sheath: 2.35 dia. mm For holding brake line: AWG22 (0.33 mm²) Outer diameter of insulating sheath: 1.37 dia. mm	
Finished Dimensions	8±0.3 dia. mm		
Internal Configuration and Lead Color	8±0.3 dia. mm		
Yaskawa Standard Specifications (Standard Length)	Cable length: 5 m, 10 m, 15	i m, 20 m, 30 m, 40 m, 50 m	

SGMAV

Encoder Cables (Length: 20 m or less)

Nama		Order No.		Charifications	Details
Name	Length	Standard Type	Flexible Type ¹	Specifications	Details
	3 m	JZSP-CSP01-03-E-G#	JZSP-CSP21-03-G#		
Cable with Connectors	5 m	JZSP-CSP01-05-E-G#	JZSP-CSP21-05-G#	Encoder end ,_, SERVOPACK end	
(For Incremental	10 m	JZSP-CSP01-10-E-G#	JZSP-CSP21-10-G#		(1)
Encoder)	15 m	JZSP-CSP01-15-E-G#	JZSP-CSP21-15-G#		
	20 m	JZSP-CSP01-20-E-G#	JZSP-CSP21-20-G#		
	3 m	JZSP-CSP05-03-E-G#	JZSP-CSP25-03-G#	SERVOPACK End Encoder End	
Cable with Connectors*2	5 m	JZSP-CSP05-05-E-G#	JZSP-CSP25-05-G#		
(For Absolute Encoder,	10 m	JZSP-CSP05-10-E-G#	JZSP-CSP25-10-G#	Battery Case	(2)
with a Battery Case)	15 m	JZSP-CSP05-15-E-G#	JZSP-CSP25-15-G#	Connector (Battery attached) Connector	
	20 m	JZSP-CSP05-20-E-G#	JZSP-CSP25-20-G#	(Crimped)(Molex Japan Co., Ltd.) (Molex Japan Co., Ltd.)	
SERVOPACK-end Connector Kit		JZSP-CMP9-1-E		Soldered	(3)
Encoder-end Connector Kit		JZSP-C	Crimped Type (A crimp tool is required.) SP-CSP9-2-E		(3)

Note: The digit "#" of the order number represents the design revision.

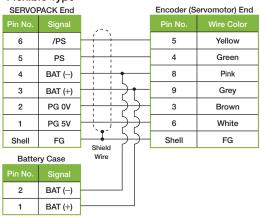
(1) Wiring Specifications for Cable with Connectors (For incremental encoder)

Flexible Type

	ACK End		Encoder (S	ervomotor) End
Pin No.	Signal	/-×	Pin No.	Wire Color
6	/PS	1	5	Yellow
5	PS		4	Green
4	BAT (-)		8	Pink
3	BAT (+)		9	Grey
2	PG 0V		3	Brown
1	PG 5V	+ + + + + + + + + + + + + + + + + + + +	6	White
Shell	FG		Shell	FG
		Shield Wire		

(2) Wiring Specifications for Cable with Connectors (For absolute encoder, with a battery case)

• Flexible Type



^{*1:} Use flexible cables for movable sections such as robot arms.
*2: When the battery is connected to the host controller, no battery case is required. If so, use a cable for incremental encoders.

(3) SERVOPACK-end/Encoder-end Connector Kit Specifications

Items	SERVOPACK-end Connector Kit	Encoder-end Connector Kit	
Order No.	JZSP-CMP9-1-E	JZSP-CSP9-2-E	
Order No.	(Cables are not included.)	(Cables are not included.)	
Manufacturer	Molex Japan Co., Ltd.	Molex Japan Co., Ltd.	
	55100-0670 (soldered)	54346-0070 (crimped)*	
	Product Specification: PS-54280	Mounting screw: M2 pan-head screw (×2)	
		Outer diameter of applicable cable: 6.3 dia. to 7.7	
		dia. mm	
Specifications		Applicable wire size: AWG22 to 26	
		Outer diameter of insulating sheath: 1.05 dia. to	
		1.4 dia. mm	
		Application Specification: AS-54992	
		Crimping Specification: CS-56161	
External Dimensions mm	(6) (12) (33)	20.5 17 2-M2 Pan-head Screws 7 1 6	

^{*:} A crimp tool is required.

The following crimp tool is applicable for the cables provided by Yaskawa. When using other wire sizes, contact the respective manufacturer for crimp tools.

Applicable crimp tool for Yaskawa's wire size: Hand Tool Model No. 57175-5000

(4) Cable Specifications

Items	Standard Type	Flexible Type			
Order No.*	JZSP-CMP09-□□-E	JZSP-CSP39-□□-E			
Cable Length	20 m max.				
	UL20276 (Rating temperature: 80°C)	UL20276 (Rating temperature: 80°C)			
	AWG22×2C+AWG24×2P	AWG22×2C+AWG24×2P			
Specifications	AWG22 (0.33 mm²)	AWG22 (0.33 mm²)			
Specifications	Outer diameter of insulating sheath: 1.15 dia. mm	Outer diameter of insulating sheath: 1.35 dia. mm			
	AWG24 (0.20 mm²)	AWG24 (0.20 mm²)			
	Outer diameter of insulating sheath: 1.09 dia. mm	Outer diameter of insulating sheath: 1.21 dia. mm			
Finished Dimensions	6.5 dia. mm	6.8 dia. mm			
Internal Configuration and Lead Color	Orange Orange/ white	Black/ light blue Red/ pink Red/ pink			
Yaskawa Standards Specifications (Standard Length)	Cable length: 5 m, 10 m, 15 m, 20 m				

Relay Encoder Cables (For extending from 30 to 50 m)

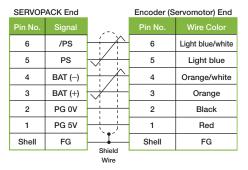
Name	Length	Order No. Standard Type	Specifications	Details
① Encoder-end Cables (For incremental and absolute encoder)	0.3 m	JZSP-CSP11-E	SERVOPACK End 0.3 m Encoder End Plug Connector (Crimped) (Molex Japan Co., Ltd.) (Molex Japan Co., Ltd.)	(1)
0	30 m	JZSP-UCMP00-30-E	SERVOPACK End Encoder End	
Cable with Connectors	40 m	JZSP-UCMP00-40-E		(2)
(For incremental and absolute encoder)	50 m	JZSP-UCMP00-50-E	Plug Connector (Crimped) Socket Connector (Soldered) (Molex Japan Co., Ltd.) (Molex Japan Co., Ltd.)	
③ Cable with a Battery Case (Required when an absolute encoder is used*.)	0.3 m	JZSP-CSP12-E	SERVOPACK End 0.3 m Encoder End Battery Case (Battery attached) Plug Connector (Crimped) Socket Connector (Soldered) (Molex Japan Co., Ltd.)	(3)
	30 m	JZSP-CMP19-30-E		
Cables	40 m	JZSP-CMP19-40-E		(4)
	50 m	JZSP-CMP19-50-E		

^{*:} Not required when connecting a battery to the host controller.

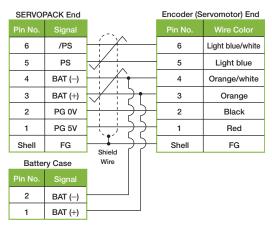
(1) Wiring Specifications for Encoder-end Cable

SERVOP	ACK End		Encoder (S	ervomotor) End
Pin No.	Signal	,-×	Pin No.	Wire Color
6	/PS	1	5	Light blue/white
5	PS	\	4	Light blue
4	BAT (-)		8	Orange/white
3	BAT (+)		9	Orange
2	PG 0V		3	Black
1	PG 5V		6	Red
Shell	FG		Shell	FG
		Shield Wire		

(2) Wiring Specifications for Cable with Connectors



(3) Wiring Specifications for Cable with a Battery Case



(4) Cable Specifications

Item	Standard Type	
Order No.	JZSP-CMP19-□□-E	
Cable Length	50 m max.	
Specifications	UL20276 (Rating temperature: 80°C) AWG16×2C+AWG26×2P AWG16 (1.31 mm²) Outer diameter of insulating sheath: 2.0 dia. mm AWG26 (0.13 mm²) Outer diameter of insulating sheath: 0.91 dia. mm	
Finished Dimensions	6.8 dia. mm	
Internal Configuration and Lead Colors	Orange Orange Awhite Red Light blue Light blue Awhite	
Yaskawa Standard Specifications (Standard Length)	Cable length: 30 m, 40 m, 50 m	

^{*:} Specify the cable length in □□ of order no. Example: JZSP-CMP19-30-E (30 m)

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